# Logical Analysis of Hybrid Systems

## **Proving Theorems for Complex Dynamics**

André Platzer (Carnegie Mellon University)

ISBN 978-3-642-14508-7, 426 pp., 99.95 Euros, 129.00 US\$

#### Comments

"This book offers a truly unique approach to hybrid systems verification with logic and theorem proving." (Edmund M. Clarke, Carnegie Mellon University)

#### Author

The author is an assistant professor in the Computer Science Department at Carnegie Mellon University. He has an M.Sc. in computer science from the University of Karlsruhe, Germany and a Ph.D. in computer science from the University of Oldenburg, Germany. Among other awards he won best paper awards at the

Tableaux 2007 and FM 2009 conferences, he was among Popular Science Magazine's annual "Brilliant 10" in 2009, he received the ACM Doctoral Dissertation Honorable Mention Award in 2009, he was among the IEEE Intelligent Systems' biennial "AI's 10 to Watch" in 2011, and he received an NSF Career award in 2011. His research interests include the logical foundations of cyberphysical systems, theorem proving and model checking.

#### Overview

Hybrid systems are models for complex physical systems and have become a widely used concept for understanding their behavior. Many applications are safety-critical, including car, railway, and air traffic control, robotics, physical-chemical process control, and biomedical devices. Hybrid systems analysis studies how we can build computerized controllers for physical systems which are guaranteed to meet their design goals.

The author gives a unique, logic-based perspective on hybrid systems analysis. It is the first book that leverages the power of logic for hybrid systems. The author develops a coherent logical approach for systematic hybrid systems analysis, covering its theory, practice, and applications. It is further shown how the developed verification techniques can be used to study air traffic and railway control systems.

This book is intended for researchers, postgraduates, and professionals who are interested in hybrid systems analysis, cyberphysical or embedded systems design, logic and theorem proving, or transportation and automation.

### **Table of Contents**

Introduction

Part I – Logics and Proof Calculi for Hybrid Systems

- Differential Dynamic Logic dL
- Differential-Algebraic Dynamic Logic DAL
- Differential Temporal Dynamic Logic dTL
- Part II Automated Theorem Proving for Hybrid Systems
- Deduction Modulo Real Algebra and Computer Algebra
- Computing Differential Invariants as Fixed Points
- Part III Case Studies and Applications in Hybrid Systems Verification
- European Train Control System
- Air Traffic Collision Avoidance

Conclusion

Part IV - Appendices

- App. A, First-Order Logic and Theorem Proving
- App. B, Differential Equations
- App. C, Hybrid Automata
- App. D, KeYmaera Implementation

References

- Index
- Operators and Proof Rules



