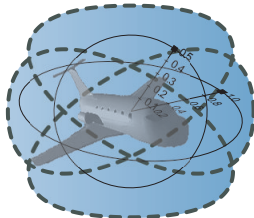


# Hybrid Systems & Complete Proofs

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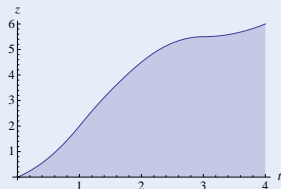
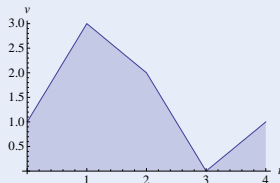
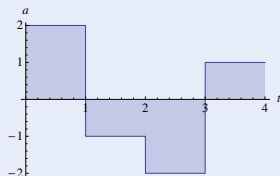
- 1 Hybrid Systems
- 2 Differential Dynamic Logic
  - Syntax
  - Semantics
  - Axiomatization
- 3 Continuous Completeness
  - Schematic Completeness
  - Expressibility and Rendition of Hybrid Programs
- 4 Discrete Completeness
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  - Discrete Completeness of  $dL + \Delta$
  - Equi-expressible
  - Relative Decidable
- 5 Summary

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## Challenge (Hybrid Systems)

Fixed rule describing state evolution with both

- Continuous dynamics (differential equations)
- Discrete dynamics (control decisions)



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- Continuous dynamics (differential equations)
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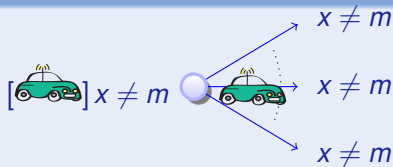
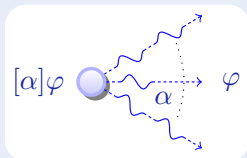


Proof theory: continuous = hybrid = discrete

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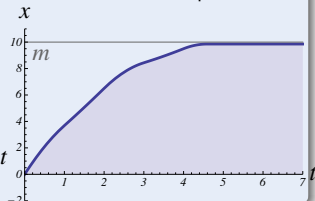
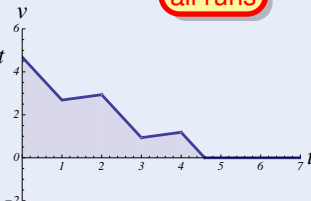
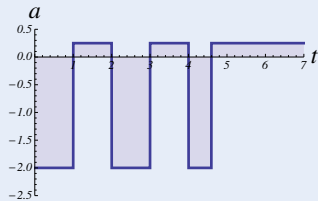
## Concept (Differential Dynamic Logic)

(JAR'08, LICS'12)



$$\underbrace{x \neq m \wedge b > 0}_{\text{init}} \rightarrow \left[ \left( \text{if}(\text{SB}(x, m)) \ a := -b \ ; \ x' = v, v' = a \right)^* \right] \underbrace{x \neq m}_{\text{post}}$$

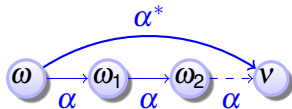
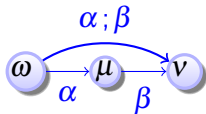
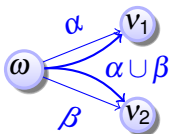
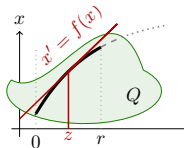
all runs





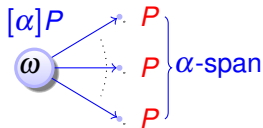
## Definition (Hybrid program)

$$\alpha, \beta ::= x := e \mid ?Q \mid x' = f(x) \& Q \mid \alpha \cup \beta \mid \alpha; \beta \mid \alpha^*$$



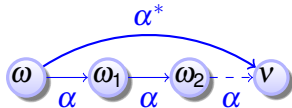
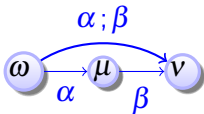
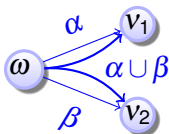
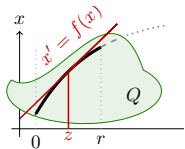
## Definition (Differential dynamic logic)

$$P, Q ::= e \geq \tilde{e} \mid \neg P \mid P \wedge Q \mid P \vee Q \mid P \rightarrow Q \mid \forall x P \mid \exists x P \mid [\alpha]P \mid \langle \alpha \rangle P$$



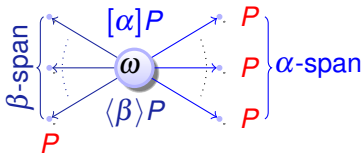
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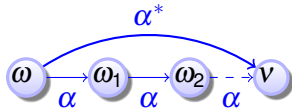
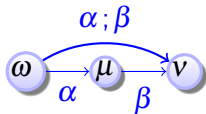
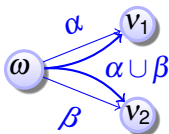
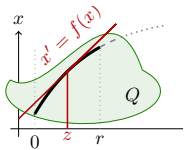
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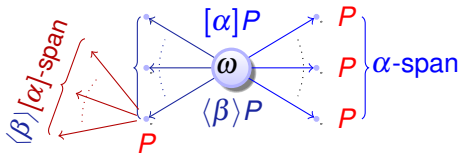
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Definition (Hybrid program semantics)

$([\cdot] : \text{HP} \rightarrow \wp(\mathcal{S} \times \mathcal{S}))$

$$[x := e] = \{(\omega, \nu) : \nu = \omega \text{ except } \nu[x] = \omega[e]\}$$

$$[?Q] = \{(\omega, \omega) : \omega \models Q\}$$

$$[x' = f(x)] = \{(\varphi(0), \varphi(r)) : \varphi \models x' = f(x) \text{ for some duration } r\}$$

$$[\alpha \cup \beta] = [\alpha] \cup [\beta]$$

$$[\alpha; \beta] = [\alpha] \circ [\beta]$$

$$[\alpha^*] = [\alpha]^* = \bigcup_{n \in \mathbb{N}} [\alpha^n]$$

compositional semantics

Definition (dL semantics)

$([\cdot] : \text{Fml} \rightarrow \wp(\mathcal{S}))$

$$[e \geq \tilde{e}] = \{\omega : \omega[e] \geq \omega[\tilde{e}]\}$$

$$[\neg P] = [P]^c$$

$$[P \wedge Q] = [P] \cap [Q]$$

$$[\langle \alpha \rangle P] = [\alpha] \circ [P] = \{\omega : \nu \models P \text{ for some } \nu : (\omega, \nu) \in [\alpha]\}$$

$$[[\alpha]P] = [\neg \langle \alpha \rangle \neg P] = \{\omega : \nu \models P \text{ for all } \nu : (\omega, \nu) \in [\alpha]\}$$

$$[\exists x P] = \{\omega : \omega_x^r \in [P] \text{ for some } r \in \mathbb{R}\}$$

$$[:=] \quad [x := e]P(x) \leftrightarrow P(e)$$

equations of truth

$$[?] \quad [?Q]P \leftrightarrow (Q \rightarrow P)$$

$$['] \quad [x' = f(x)]P \leftrightarrow \forall t \geq 0 [x := y(t)]P \quad (y'(t) = f(y))$$

$$[\cup] \quad [\alpha \cup \beta]P \leftrightarrow [\alpha]P \wedge [\beta]P$$

$$[;] \quad [\alpha; \beta]P \leftrightarrow [\alpha][\beta]P$$

$$[*] \quad [\alpha^*]P \leftrightarrow P \wedge [\alpha][\alpha^*]P$$

$$K \quad [\alpha](P \rightarrow Q) \rightarrow ([\alpha]P \rightarrow [\alpha]Q)$$

laws of logic of  
laws of physics

$$I \quad [\alpha^*]P \leftrightarrow P \wedge [\alpha^*](P \rightarrow [\alpha]P)$$

$$C \quad [\alpha^*]\forall v > 0 (P(v) \rightarrow \langle \alpha \rangle P(v-1)) \rightarrow \forall v (P(v) \rightarrow \langle \alpha^* \rangle \exists v \leq 0 P(v))$$

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$$\text{G} \quad \frac{P}{[\alpha]P}$$

$$\forall \quad \frac{P}{\forall x P}$$

$$\text{MP} \quad \frac{P \rightarrow Q \quad P}{Q}$$

rules of truth

laws of logic of  
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$$G \frac{P}{[\alpha]P}$$

rules of truth

$$\forall \frac{P}{\forall x P}$$

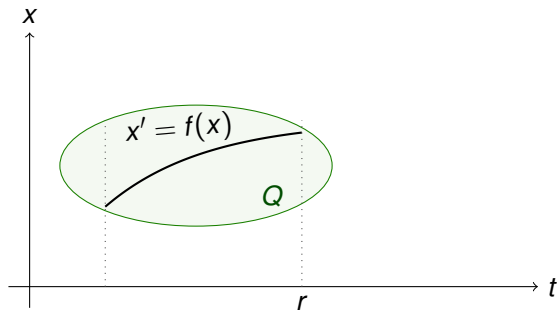
$$MP \frac{P \rightarrow Q \quad P}{Q}$$

$$B \quad \forall x [\alpha]P \rightarrow [\alpha]\forall x P \quad (x \notin \alpha)$$

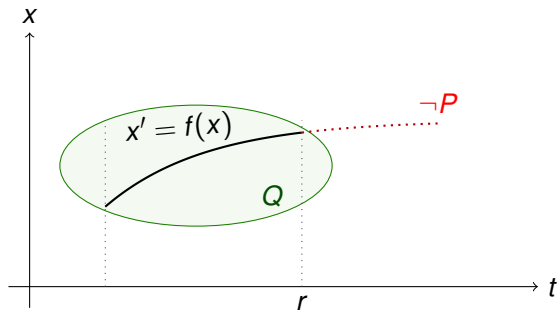
$$\forall \quad p \rightarrow [\alpha]p \quad (FV(p) \cap BV(\alpha) = \emptyset)$$

laws of logic of  
laws of physics

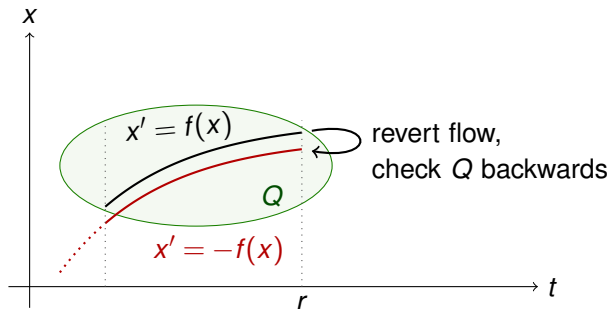
$$[\&] \quad [x' = f(x) \& Q]P \\ \leftrightarrow \quad [x' = f(x)](P)$$



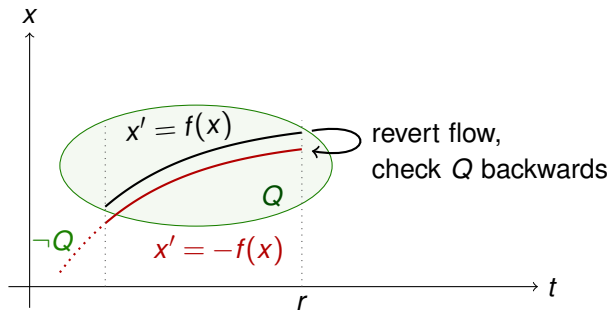
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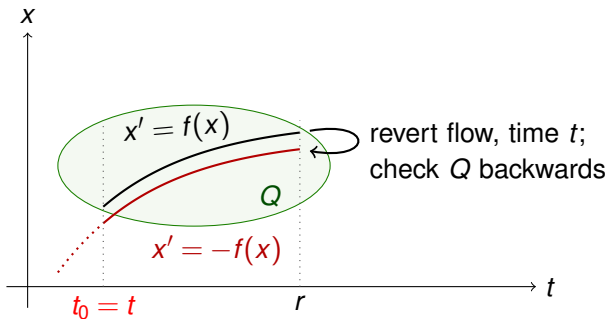
$$[\&] \quad [x' = f(x) \& Q]P \\ \leftrightarrow \quad [x' = f(x)]([x' = -f(x)](Q) \rightarrow P)$$



$$[\&] \quad [x' = f(x) \& Q]P \\ \leftrightarrow \quad [x' = f(x)]([x' = -f(x)](Q) \rightarrow P)$$

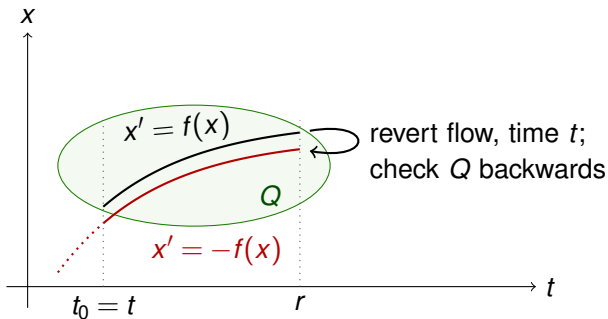


$$[\&] \quad [x' = f(x) \& Q]P \\ \leftrightarrow \forall t_0 = t [x' = f(x)] ([x' = -f(x)] (t \geq t_0 \rightarrow Q) \rightarrow P)$$



# A “There and Back Again” Axiom of dL

$$[\&] \quad [x' = f(x) \& Q]P \\ \leftrightarrow \forall t_0 = t [x' = f(x)] ([x' = -f(x)](t \geq t_0 \rightarrow Q) \rightarrow P)$$



## Lemma

*Evolution domain axiomatizable*

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Theorem (Relative Completeness / Continuous) (JAR'08,LICS'12)

*dL calculus is a sound & complete axiomatization of hybrid systems relative to differential equations:*

$\models \varphi$  iff  $\text{Taut}_{\text{FOD}} \vdash \varphi$

Corollary (Complete Proof-theoretical Alignment)

proving: continuous = hybrid

Corollary (Compositionality)

hybrid systems can be verified by recursive decomposition

$$\text{FOD} = \text{FOL} + [x' = f(x)]F$$

Theorem (Relative Completeness / Continuous) (JAR'08,LICS'12)

dL calculus is a sound & complete axiomatization of hybrid systems relative to *differential equations*:  
 $\models \varphi$  iff  $\text{Taut}_{\text{FOD}} \vdash \varphi$

Theorem (Relative Completeness / Discrete) (LICS'12)

dL calculus is a sound & complete axiomatization of hybrid systems relative to *discrete dynamics*:  
 $\models \varphi$  iff  $\text{Taut}_{\text{DL}} \vdash \varphi$

Corollary (Complete Proof-theoretical Alignment)

proving: continuous = hybrid = discrete

Corollary (Interdisciplinary Integrability)

“Discrete mathematics + continuous mathematics are integrable”

Theorem (Relative Completeness / Continuous) (JAR'08,LICS'12)

dL calculus is a sound & complete axiomatization of hybrid systems relative to *differential equations*:  $\models \varphi$  iff  $\text{Taut}_{\text{FOD}} \vdash \varphi$

Theorem (Relative Completeness / Discrete) (LICS'12)

dL calculus is a sound & complete axiomatization of hybrid systems relative to *discrete dynamics*:  $\models \varphi$  iff  $\text{Taut}_{\text{DL}} \vdash \varphi$

Theorem (Schematic Completeness) (JAR'17)

dL calculus is a sound & complete axiomatization of hybrid systems relative to *any (differentially) expressive logic L*:  $\models \varphi$  iff  $\text{Taut}_L \vdash \varphi$

Differentially expressive

$\forall \varphi \in \text{dL} \exists \varphi^b \in L \models \varphi \leftrightarrow \varphi^b$  and  $\forall \varphi \in L \vdash_L \langle x' = f(x) \rangle \varphi \leftrightarrow (\langle x' = f(x) \rangle \varphi)^b$

Proof of “continuous = hybrid = discrete”

Proof Sketch ( $\phi$  in NNF, induction on well-founded  $\prec$ ) (JAR'17).

- 0  $\phi$  first-order formula  $\Rightarrow \phi \in L$  so  $\vdash_L \phi$  if  $\models \phi$  (Also for  $\neg\phi_1$  by NNF)
- 1  $\phi \equiv \phi_1 \wedge \phi_2 \Rightarrow \models \phi_1$  and  $\models \phi_2 \stackrel{\text{IH}}{\Rightarrow} \vdash_L \phi_1$  and  $\vdash_L \phi_2 \Rightarrow \vdash_L \phi_1 \wedge \phi_2$ .
- 2  $\phi \equiv \exists x \phi_2, \forall x \phi_2, \langle \alpha \rangle \phi_2$  or  $[\alpha] \phi_2$  covered in next case with  $\phi_1 \equiv \text{false}$ .
- 3  $\phi \equiv \phi_1 \vee \langle [\alpha] \rangle \phi_2$  is (by associativity and commutativity to reorder):

$$\begin{array}{ll} \phi_1 \vee \langle \alpha \rangle \phi_2 & \phi_1 \vee \exists x \phi_2 \\ \phi_1 \vee [\alpha] \phi_2 & \phi_1 \vee \forall x \phi_2 \end{array}$$

Then,  $\phi_2 \prec \phi$  and  $\phi_1 \prec \phi$  as less HP/quantifier. Let  $F \equiv \neg\phi_1$  and  $G \equiv \phi_2$  then  $\models F \rightarrow \langle [\alpha] \rangle G$ . Show  $\vdash_L F \rightarrow \langle [\alpha] \rangle G$ , which derives  $\vdash_L \phi_1 \vee \langle [\alpha] \rangle \phi_2$ .

$$\vdash_L \phi \text{ iff } \text{Taut}_L \vdash \phi$$

$\prec$  is lexicographic order of HP, formula, with  $L$  at the bottom



Proof Sketch ( $\phi$  in NNF, induction on well-founded  $\prec$ ) (JAR'17).

- ④  $\langle \alpha \rangle \equiv \forall x$  with  $\models F \rightarrow \forall x G$ , wlog  $x \notin F$  by bound variable renaming.

Hence,  $\models F \rightarrow G \stackrel{\text{IH}}{\Rightarrow} \vdash_L F \rightarrow G$  as  $(F \rightarrow G) \prec (F \rightarrow \forall x G)$  less  $\forall$ .

$$\frac{\frac{\frac{F \rightarrow G}{\forall x (F \rightarrow G)}}{\forall x F \rightarrow \forall x G}}{\forall x F \rightarrow \forall x G}}$$

- ⑤  $\langle \alpha \rangle \equiv \exists x$  with  $\models F \rightarrow \exists x G$ . Have  $\models G^b \leftrightarrow G \Rightarrow \models F \rightarrow \exists x (G^b) \stackrel{\text{IH}}{\Rightarrow} \vdash_L F \rightarrow \exists x (G^b)$  as  $(F \rightarrow \exists x (G^b)) \prec (F \rightarrow \exists x G)$  as  $G^b \in L$ . Also

$\models G^b \leftrightarrow G \Rightarrow \models G^b \rightarrow G \stackrel{\text{IH}}{\Rightarrow} \vdash_L G^b \rightarrow G$  since  $(G^b \rightarrow G) \prec \phi$  as  $G^b \in L$ .

$$\frac{\frac{\frac{F \rightarrow \exists x (G^b)}{\exists x (G^b) \rightarrow \exists x G}}{\exists x (G^b) \rightarrow \exists x G}}{\exists x (G^b) \rightarrow \exists x G}}{\frac{F \rightarrow \exists x (G^b)}{F \rightarrow \exists x G}} \text{MP}}$$

□

Proof Sketch ( $\phi$  in NNF, induction on well-founded  $\prec$ ) (JAR'17).

- 6  $\models F \rightarrow \langle x' = f(x) \rangle G$  implies  $\models F \rightarrow (\langle x' = f(x) \rangle G^b)^b \stackrel{\text{IH}}{\Rightarrow}$   
 $\vdash_L F \rightarrow (\langle x' = f(x) \rangle G^b)^b$  as  $(\langle x' = f(x) \rangle G^b)^b \in L$  is smaller.  
 $\vdash_L \langle x' = f(x) \rangle G^b \leftrightarrow (\langle x' = f(x) \rangle G^b)^b$  as L differentially expressive.  
 By IH  $\vdash_L G^b \rightarrow G$  as  $G^b \in L$ . So  $\vdash_L \langle x' = f(x) \rangle G^b \rightarrow \langle x' = f(x) \rangle G$  by M.  
 Thus  $\vdash_L F \rightarrow \langle x' = f(x) \rangle G$  propositionally.
- 7  $\models F \rightarrow [?Q]G$  implies  $\models F \rightarrow (Q \rightarrow G) \stackrel{\text{IH}}{\Rightarrow} \vdash_L F \rightarrow (Q \rightarrow G)$  since  
 $(Q \rightarrow G) \prec [?Q]G$ . Thus  $\vdash_L F \rightarrow [?Q]G$  as  $[?Q]G \leftrightarrow (Q \rightarrow G)$  by [?].
- 8  $\models F \rightarrow [\beta \cup \gamma]G$  implies  $\models F \rightarrow [\beta]G \wedge [\gamma]G \stackrel{\text{IH}}{\Rightarrow} \vdash_L F \rightarrow [\beta]G \wedge [\gamma]G$  as  
 $[\beta]G \wedge [\gamma]G \prec [\beta \cup \gamma]G$  has smaller HP. Thus  $\vdash_L F \rightarrow [\beta \cup \gamma]G$  by [U].
- 9  $\models F \rightarrow [\beta; \gamma]G$  implies  $\models F \rightarrow [\beta][\gamma]G \stackrel{\text{IH}}{\Rightarrow} \vdash_L F \rightarrow [\beta][\gamma]G$  as  
 $[\beta][\gamma]G \prec [\beta; \gamma]G$  has smaller HP. Thus  $\vdash_L F \rightarrow [\beta; \gamma]G$  by [;].

□

Proof Sketch ( $\phi$  in NNF, induction on well-founded  $\prec$ ) (JAR'17).

- ⑩  $\models F \rightarrow [y := \theta]G$ . Rename bound variable to fresh variable  $x$  where  $G_y^x$  is the result of uniformly renaming  $y$  to  $x$  in  $G$ :

$$\begin{array}{c} \frac{F \rightarrow \forall x (x = \theta \rightarrow G_y^x)}{[:=]_ = F \rightarrow [x := \theta]G_y^x} \\ \text{BR} \frac{}{F \rightarrow [y := \theta]G} \end{array}$$

using the derivable equational form of the assignment axiom  $[:=]_ =$

$$[:=]_ = [x := f]P \leftrightarrow \forall x (x = f \rightarrow P)$$

Only used equivalences, so premise valid iff conclusion valid.

$\models F \rightarrow \forall x (x = \theta \rightarrow G_y^x) \stackrel{\text{IH}}{\Rightarrow} \vdash_L F \rightarrow \forall x (x = \theta \rightarrow G_y^x)$  as  
 $(F \rightarrow \forall x (x = \theta \rightarrow G_y^x)) \prec (F \rightarrow [y := \theta]G)$  has less modalities.





Proof Sketch ( $\phi$  in NNF, induction on well-founded  $\prec$ ) (JAR'17).

①  $\models F \rightarrow [\beta^*]G$ . Formula  $[\beta^*]G$  is loop invariant as  $\models [\beta^*]G \rightarrow [\beta][\beta^*]G$ .

$J \equiv ([\beta^*]G)^b$  equivalent loop invariant in simpler  $L$

Then  $\models F \rightarrow J$  and  $\models J \rightarrow G \stackrel{\text{IH}}{\Rightarrow} \vdash_L F \rightarrow J$  and  $\vdash_L J \rightarrow G$  since  $(F \rightarrow J) \prec \phi$  and  $(J \rightarrow G) \prec \phi$  as  $J \in L$  is smaller.

Moreover  $\models J \rightarrow [\beta]J \stackrel{\text{IH}}{\Rightarrow} \vdash_L J \rightarrow [\beta]J$  since  $\beta$  has less loops than  $\beta^*$ .

$$\begin{array}{c}
 \frac{F \rightarrow J \quad \text{MP} \frac{\text{ind} \frac{J \rightarrow [\beta]J}{J \rightarrow [\beta^*]J} \quad \text{M}[\cdot] \frac{J \rightarrow G}{[\beta^*]J \rightarrow [\beta^*]G}}{J \rightarrow [\beta^*]G}}{F \rightarrow [\beta^*]G} \\
 \text{MP}
 \end{array}$$

□

Proof Sketch ( $\phi$  in NNF, induction on well-founded  $\prec$ ) (JAR'17).

⑫  $\models F \rightarrow \langle \beta^* \rangle G$ . Let  $x = \text{FV}(\langle \beta^* \rangle G)$ . Since  $\langle \beta^* \rangle G$  is a least pre-fixpoint:

$$\models \forall x (G \vee \langle \beta \rangle p(x) \rightarrow p(x)) \rightarrow (\langle \beta^* \rangle G \rightarrow p(x))$$

As  $\models F \rightarrow \langle \beta^* \rangle G$  also  $\models \forall x (G \vee \langle \beta \rangle p(x) \rightarrow p(x)) \rightarrow (F \rightarrow p(x)) \stackrel{\text{IH}}{\Rightarrow}$

$\vdash_{\perp} \forall x (G \vee \langle \beta \rangle p(x) \rightarrow p(x)) \rightarrow (F \rightarrow p(x))$  as

$(\forall x (G \vee \langle \beta \rangle p(x) \rightarrow p(x)) \rightarrow (F \rightarrow p(x))) \prec \phi$ .  $\sigma = \{p(x) \mapsto \langle \beta^* \rangle G\}$

admissible since  $\text{FV}(\sigma) = \emptyset$  as  $x = \text{FV}(\langle \beta^* \rangle G)$  and since  $p$  is fresh:

$$\text{MP} \frac{\text{US} \frac{\forall x (G \vee \langle \beta \rangle p(x) \rightarrow p(x)) \rightarrow (F \rightarrow p(x)) \quad \overset{*}{\frac{G \vee \langle \beta \rangle \langle \beta^* \rangle G \rightarrow \langle \beta^* \rangle G}{\forall x (G \vee \langle \beta \rangle \langle \beta^* \rangle G \rightarrow \langle \beta^* \rangle G)}}{[\cdot], \langle \cdot \rangle} \frac{\forall x (G \vee \langle \beta \rangle \langle \beta^* \rangle G \rightarrow \langle \beta^* \rangle G) \rightarrow (F \rightarrow \langle \beta^* \rangle G)}{\forall x (G \vee \langle \beta \rangle \langle \beta^* \rangle G \rightarrow \langle \beta^* \rangle G)}}{F \rightarrow \langle \beta^* \rangle G}}$$

Note: could also use modified  $(\langle \beta^* \rangle G)^{\flat}$  with convergence rule con. □

Theorem (Relative Completeness / Continuous) (JAR'08,LICS'12)

*dL calculus is a sound & complete axiomatization of hybrid systems relative to differential equations:*

$\models \varphi$  iff  $\text{Taut}_{\text{FOD}} \vdash \varphi$

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dL calculus is a sound & complete axiomatization of hybrid systems relative to *differential equations*:  $\models \varphi$  iff  $\text{Taut}_{\text{FOD}} \vdash \varphi$

Theorem (Schematic Completeness) (JAR'17)

dL calculus is a sound & complete axiomatization of hybrid systems relative to *any (differentially) expressive logic L*:  $\models \varphi$  iff  $\text{Taut}_L \vdash \varphi$

Differentially expressive

$\forall \varphi \in \text{dL} \exists \varphi^b \in L \models \varphi \leftrightarrow \varphi^b$  and  $\forall \varphi \in L \vdash_L \langle x' = f(x) \rangle \varphi \leftrightarrow (\langle x' = f(x) \rangle \varphi)^b$

## Lemma (dL Expressibility in FOD)

$\forall \varphi \in \text{dL} \exists \varphi^b \in \text{FOD} \models \varphi \leftrightarrow \varphi^b$  and  $\forall \varphi \in \text{FOD} \vdash_L \langle x' = f(x) \rangle \varphi \leftrightarrow (\langle x' = f(x) \rangle \varphi)^b$

## Proof Sketch.

- 1 Strong enough invariants and variants expressible in dL!
- 2 dL expressible in FOD?
- 3 Finite FOD formula characterizing unbounded hybrid repetition.
- 4 FOD characterizes  $\mathbb{R}$ -Gödel encoding (pairing/unpairing on  $\mathbb{R}$ ).
- 5 FOD characterizes HP transitions.
- 6 FOD expresses dL formulas. □

$$\text{FOD} = \text{FOL}_{\mathbb{R}} + [x' = f(x)]F$$

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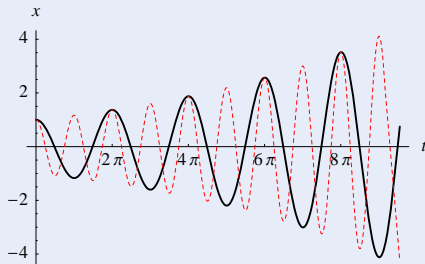
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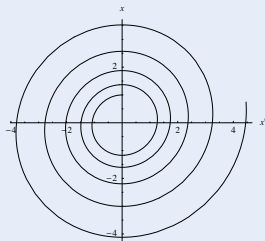
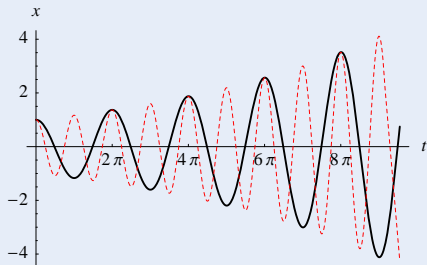
FOD characterizes constructive bijection  $\mathbb{R} \rightarrow \mathbb{R}^2$



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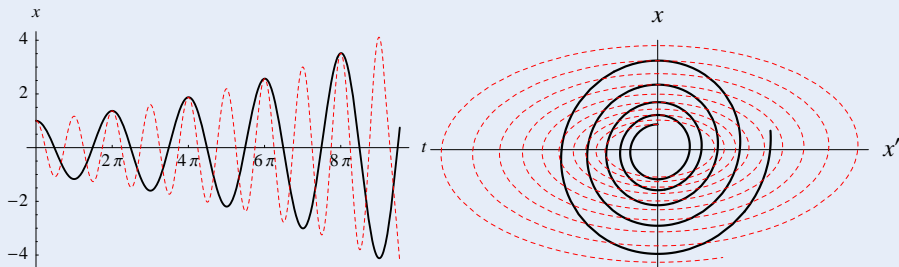
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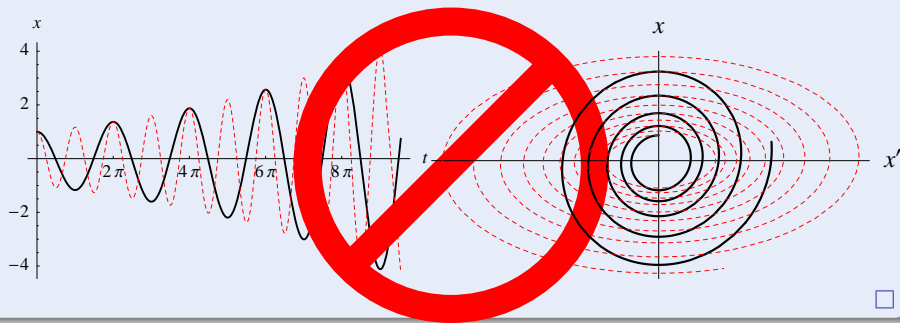
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Proof Sketch ( $\mathbb{R}$ -Gödel encoding).

FOD characterizes constructive bijection  $\mathbb{R} \rightarrow \mathbb{R}^2$  **not differentiable, Morayne!**



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Proof Sketch ( $\mathbb{R}$ -Gödel encoding).

FOD characterizes constructive bijection  $\mathbb{R} \rightarrow \mathbb{R}^2$

$$\begin{array}{l} \sum_{i=0}^{\infty} \frac{a_i}{2^i} = a_0.a_1a_2\dots \\ \sum_{i=0}^{\infty} \frac{b_i}{2^i} = b_0.b_1b_2\dots \end{array} \quad \begin{array}{c} \swarrow \\ \searrow \end{array} \quad \sum_{i=0}^{\infty} \left( \frac{a_i}{2^{2i-1}} + \frac{b_i}{2^{2i}} \right) = a_0b_0.a_1b_1a_2b_2\dots$$



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**$Z_j^{(n)} = z$  is  $j$ th  $\mathbb{R}$  of  $n$  reals  $Z$**

$$\text{at}(Z, n, j, z) \leftrightarrow \forall i: \mathbb{Z} \text{ digit}(z, i) = \text{digit}(Z, n(i-1) + j) \wedge n > 0 \wedge n, j \in \mathbb{N}$$

$$\text{digit}(a, i) = \text{intpart}(2 \text{frac}(2^{i-1} a))$$

$$\text{intpart}(a) = a - \text{frac}(a)$$

$$\text{frac}(a) = z \leftrightarrow \exists i: \mathbb{Z} z = a - i \wedge -1 < z \wedge z < 1 \wedge az \geq 0 \quad \text{“keep sign”} \quad \square$$

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$$2^i = z \leftrightarrow i \geq 0 \wedge \langle x := 1; t := 0; x' = x \ln 2, t' = 1 \rangle (t = i \wedge x = z) \\ \vee i < 0 \wedge \langle x := 1; t := 0; x' = -x \ln 2, t' = -1 \rangle (t = i \wedge x = z)$$

$$\ln 2 = z \leftrightarrow \langle x := 1; t := 0; x' = x, t' = 1 \rangle (x = 2 \wedge t = z)$$

syntactic abbreviation without recursion





## Lemma (dL Expressibility in FOD)

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## Lemma (Program rendition)

$\forall \alpha \in \text{HP}$  with variables among  $x = x_1, \dots, x_k$   $\exists \mathcal{S}_\alpha(x, v) \in \text{FOD}$  with variables among distinct  $x = x_1, \dots, x_k$  and  $v = v_1, \dots, v_k$ :  $\models \mathcal{S}_\alpha(x, v) \leftrightarrow \langle \alpha \rangle x = v$

## Proof Sketch (by induction on $\alpha$ ).

$$\mathcal{S}_{x_i := \theta}(x, v) \equiv v_i = \theta \wedge \bigwedge_{j \neq i} (v_j = x_j)$$

$$\mathcal{S}_{x' = \theta}(x, v) \equiv \langle x' = \theta \rangle v = x$$

$$\mathcal{S}_{x' = \theta \& Q}(x, v) \equiv \exists t (t = 0 \wedge \langle x' = \theta, t' = 1 \rangle (v = x \wedge [x' = -\theta, t' = -1] (t \geq 0 \rightarrow Q)))$$

$$\mathcal{S}_{?Q}(x, v) \equiv v = x \wedge Q$$

$$\mathcal{S}_{\beta \cup \gamma}(x, v) \equiv \mathcal{S}_\beta(x, v) \vee \mathcal{S}_\gamma(x, v)$$

$$\mathcal{S}_{\beta; \gamma}(x, v) \equiv \exists z (\mathcal{S}_\beta(x, z) \wedge \mathcal{S}_\gamma(z, v))$$

$$\mathcal{S}_{\beta^*}(x, v) \equiv \exists Z \exists n: \mathbb{N} (Z_1^{(n)} = x \wedge Z_n^{(n)} = v \wedge \forall i: \mathbb{N} (1 \leq i < n \rightarrow \mathcal{S}_\beta(Z_i^{(n)}, Z_{i+1}^{(n)})))$$



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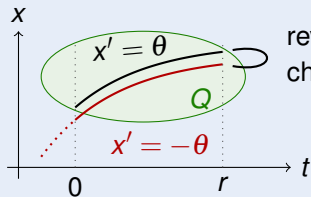


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$$\begin{aligned} \mathcal{S}_{x'=\theta \& Q}(x, v) &\equiv \exists t (t=0 \wedge \langle x'=\theta, t'=1 \rangle (v=x \wedge [x'=-\theta, t'=-1](t \geq 0 \rightarrow Q))) \\ &\equiv \exists t \exists r (t=0 \wedge \langle x'=\theta, t'=1 \rangle (v=x \wedge r=t) \wedge \\ &\quad \forall x \forall t (x=v \wedge t=r \rightarrow [x'=-\theta, t'=-1](t \geq 0 \rightarrow Q))) \end{aligned}$$



revert flow and time  
check  $Q$  backwards



## Lemma (dL Expressibility in FOD)

$$\forall \varphi \in \text{dL} \exists \varphi^b \in \text{FOD} \models \varphi \leftrightarrow \varphi^b$$

Proof (by induction on  $\varphi$ ).

- 1  $\varphi$  first-order, then  $\varphi^b := \varphi$  already is a FOD-formula.
- 2  $\varphi \equiv \phi \vee \psi \stackrel{\text{IH}}{\Rightarrow}$  have  $\phi^b, \psi^b$  such that  $\models \phi \leftrightarrow \phi^b$  and  $\models \psi \leftrightarrow \psi^b$ . By congruence  $\models (\phi \vee \psi) \leftrightarrow (\phi^b \vee \psi^b)$  giving  $\models \varphi \leftrightarrow \varphi^b$  for  $\varphi^b \equiv \phi^b \vee \psi^b$ .
- 3 Likewise for propositional connectives or quantifiers.
- 4  $\varphi \equiv \langle \alpha \rangle \psi$  uses  $\models \langle \alpha \rangle \psi \leftrightarrow \exists v (\mathcal{S}_\alpha(x, v) \wedge \psi^b \frac{v}{x})$
- 5  $\varphi \equiv [\alpha] \psi$  uses  $\models [\alpha] \psi \leftrightarrow \forall v (\mathcal{S}_\alpha(x, v) \rightarrow \psi^b \frac{v}{x})$  □

- 1 Hybrid Systems
- 2 Differential Dynamic Logic
  - Syntax
  - Semantics
  - Axiomatization
- 3 Continuous Completeness
  - Schematic Completeness
  - Expressibility and Rendition of Hybrid Programs
- 4 Discrete Completeness
  - Open Discrete Completeness
  - Closed Discrete Completeness
  - Semialgebraic Discrete Completeness of  $dL + \Delta$
  - Discrete Completeness of  $dL + \Delta$
  - Equi-expressible
  - Relative Decidable
- 5 Summary



Theorem (Relative Completeness / Continuous) (JAR'08,LICS'12)

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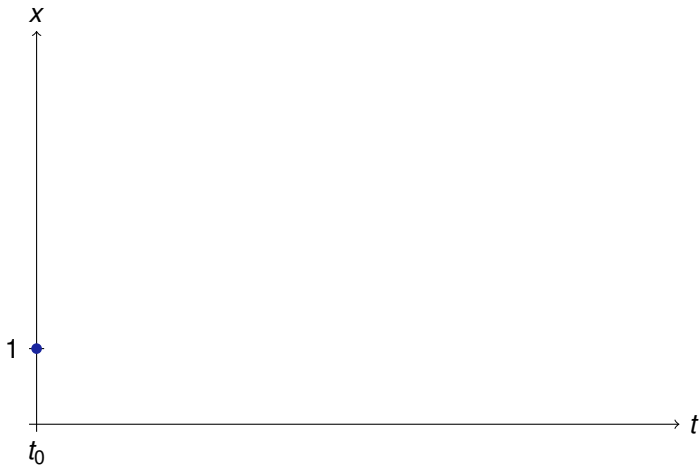
Theorem (Relative Completeness / Discrete) (LICS'12)

dL calculus is a sound & complete axiomatization of hybrid systems relative to *discrete dynamics*:  
 $\models \varphi$  iff  $\text{Taut}_{\text{DL}} \vdash \varphi$

Corollary (Complete Proof-theoretical Alignment)

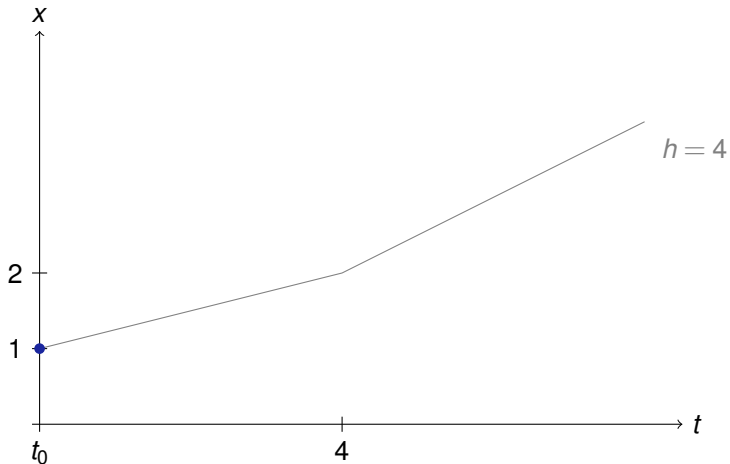
proving: continuous = hybrid = discrete

$$\left[x' = \frac{x}{4}\right]F$$

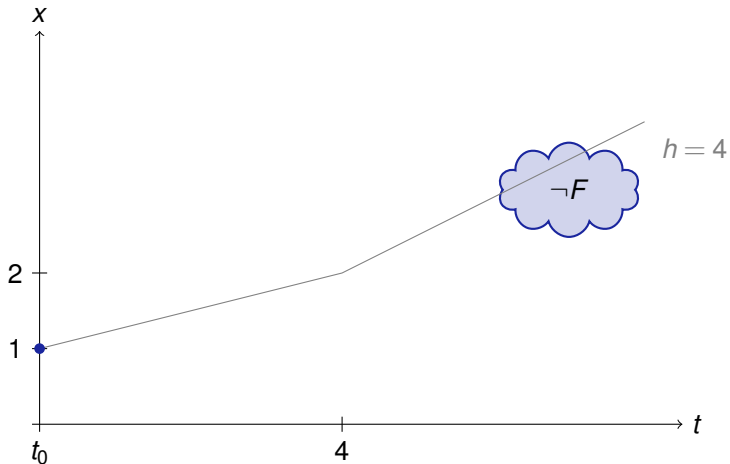


$$[x' = \frac{x}{4}]F$$

$$[(x := x + h\frac{x}{4})^*]F$$

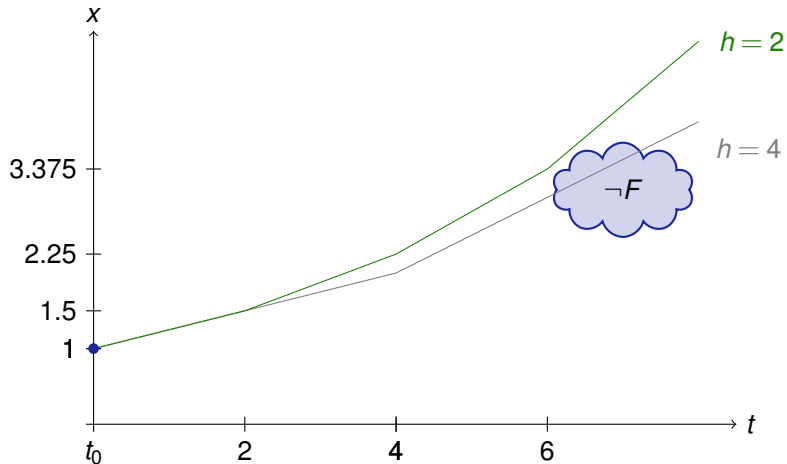


$$[x' = \frac{x}{4}]F \not\equiv [(x := x + h\frac{x}{4})^*]F$$



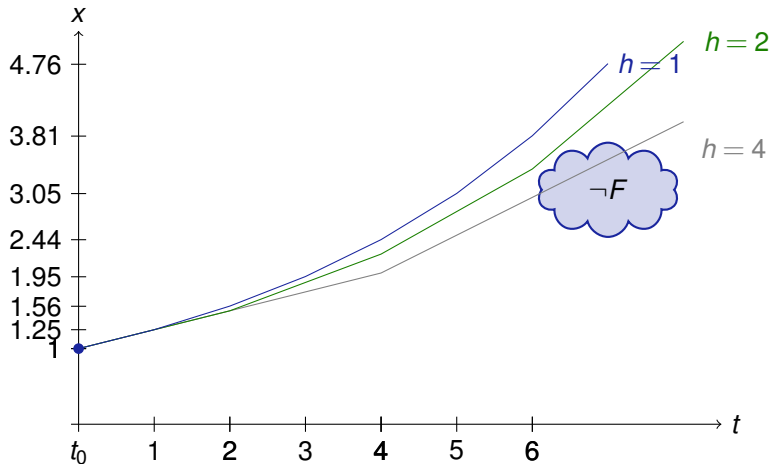
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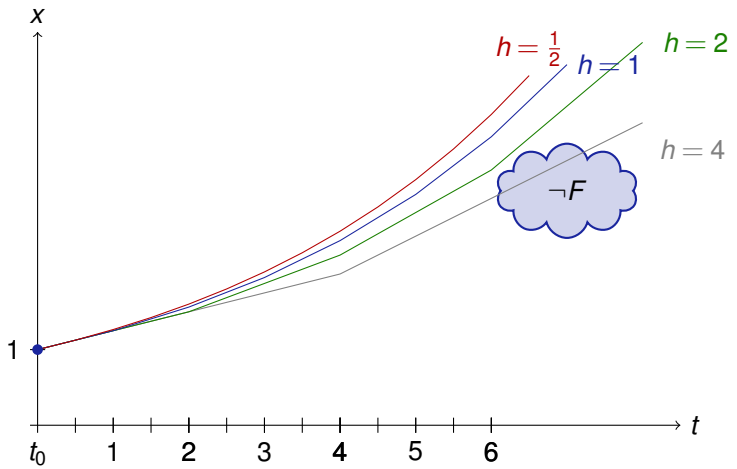
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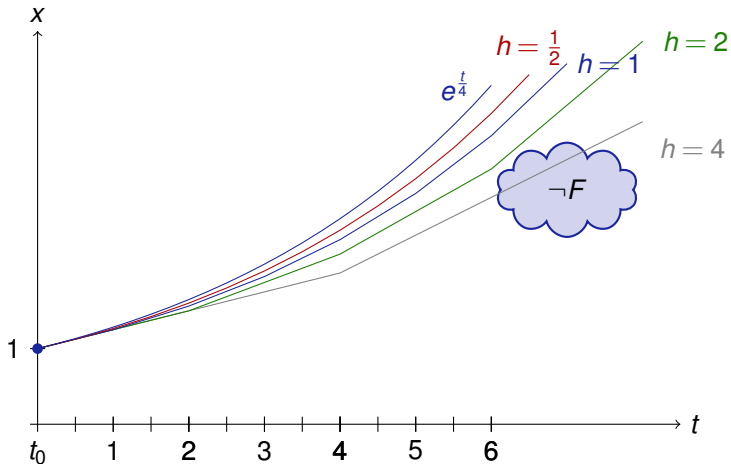


$$[x' = \frac{x}{4}]F$$

$$[(x := x + h\frac{x}{4})^*]F$$

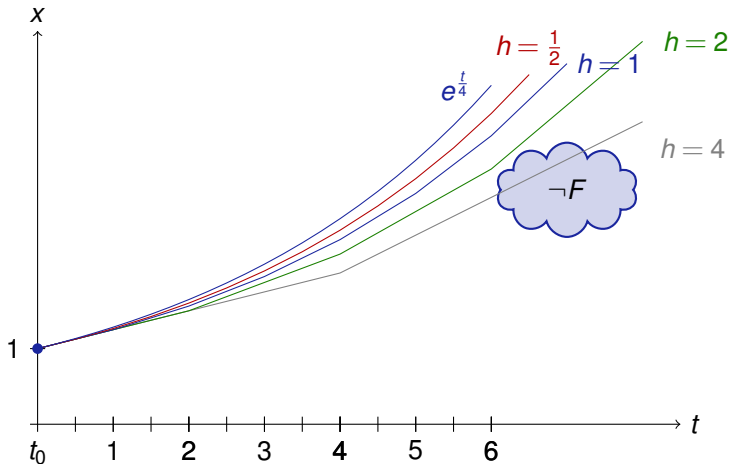


$$\left[x' = \frac{x}{4}\right]F \quad \text{vs.} \quad \left[(x := x + h\frac{x}{4})^*\right]F$$

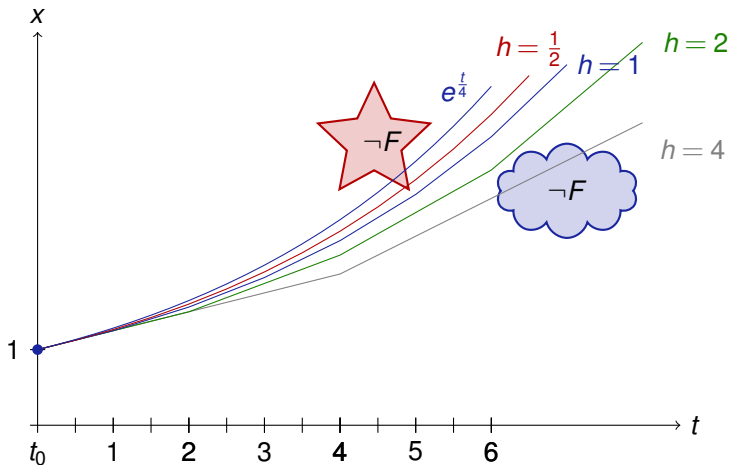




$$\left[x' = \frac{x}{4}\right]F \not\Rightarrow \left[(x := x + h\frac{x}{4})^*\right]F$$



$$[x' = \frac{x}{4}]F \neq [(x := x + h\frac{x}{4})^*]F$$



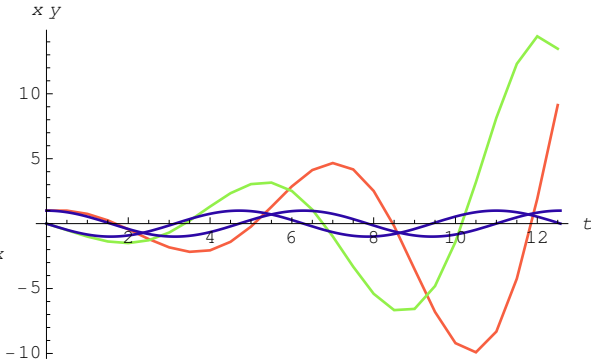
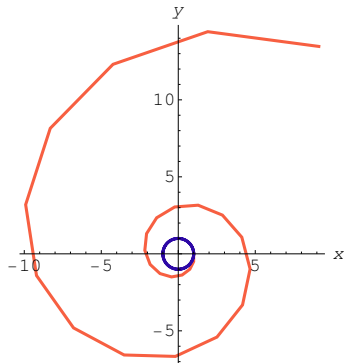
$$\overleftarrow{\Delta} \quad [x' = f(x)]F \\ \leftarrow \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*]F$$

$$\overleftarrow{\Delta} [x' = f(x)]F$$

$$\leftarrow \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*]F$$

Example (Incomplete, not global)

$$\models x^2 + y^2 \leq 1 \rightarrow [x' = y, y' = -x]x^2 + y^2 \leq 1.1$$



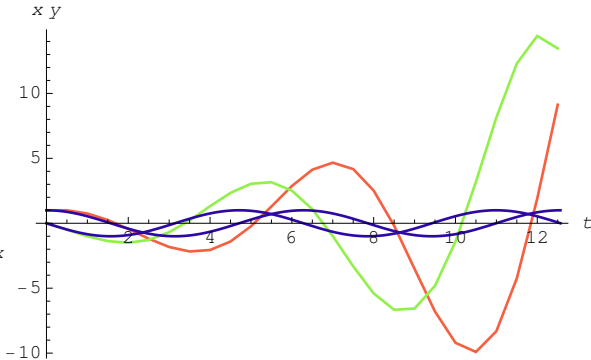
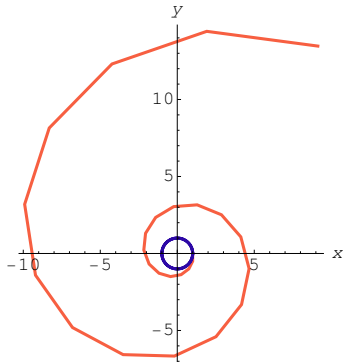
$$\overleftarrow{\Delta} [x' = f(x)]F$$

$$\leftarrow \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*]F$$

(closed)

Example (Unsound for open  $F$ , only in closure)

$$\not\models x = 1 \wedge y = 0 \rightarrow [x' = y, y' = -x](x \leq 0 \rightarrow x^2 + y^2 > 1)$$

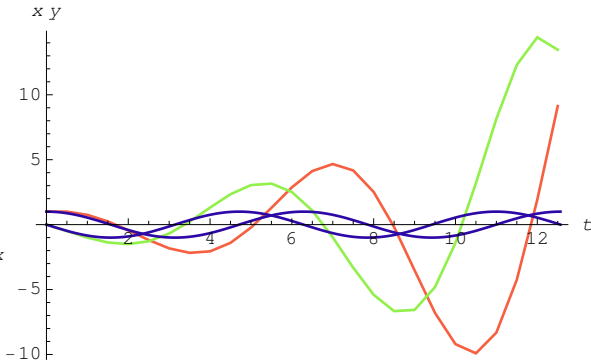
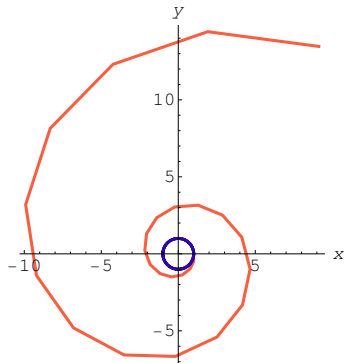


$$\overleftarrow{\Delta} \quad [x' = f(x)]F \quad (\text{closed})$$

$$\leftarrow \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*]F$$

Example (Incomplete, not global)

$$\models x^2 + y^2 \leq 1 \rightarrow [x' = y, y' = -x]x^2 + y^2 \leq 1.1$$

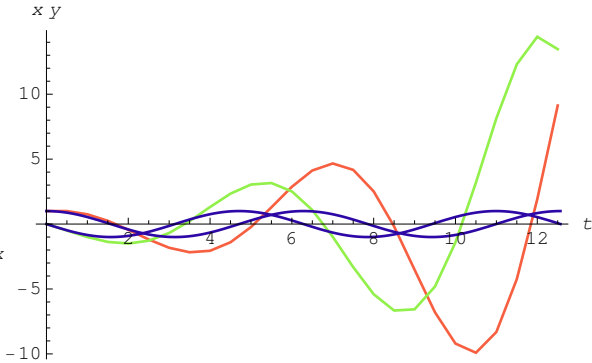
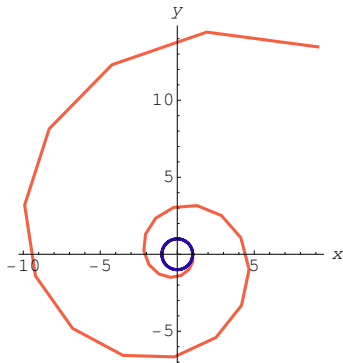


$$\overrightarrow{\Delta} \quad [x' = f(x)]F \\ \rightarrow \forall t \geq 0 \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*](t \geq 0 \rightarrow F)$$

$$\overrightarrow{\Delta} [x' = f(x)]F \rightarrow \forall t \geq 0 \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*](t \geq 0 \rightarrow F)$$

Example (Converse of  $\overrightarrow{\Delta}$  unsound for open  $F$  closed  $F$  by  $\overleftarrow{\Delta}$ )

$$\not\models x = 1 \wedge y = 0 \rightarrow [x' = y, y' = -x](x \leq 0 \rightarrow x^2 + y^2 > 1)$$

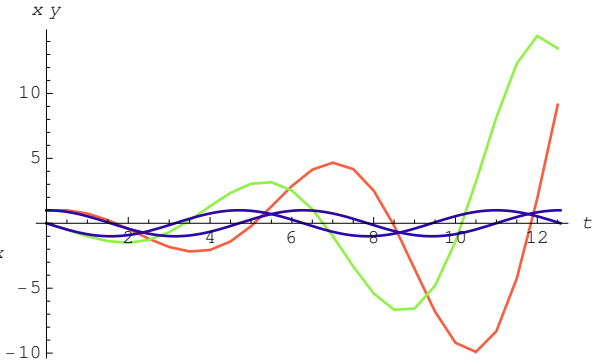
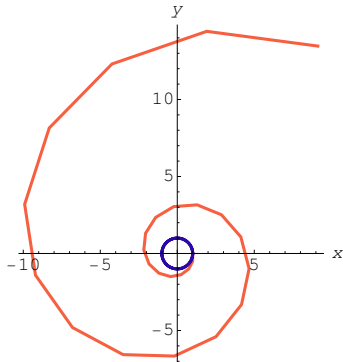




$$\overrightarrow{\Delta} [x' = f(x)]F \rightarrow \forall t \geq 0 \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*](t \geq 0 \rightarrow F) \quad (\text{open})$$

Example (Unsound for closed  $F$ , only holds in the limit)

$$\models x^2 + y^2 = 1 \rightarrow [x' = y, y' = -x]x^2 + y^2 = 1$$



$$\overleftrightarrow{\Delta} \quad [x' = f(x)]F$$

$$\Leftrightarrow \forall t \geq 0 \exists \varepsilon > 0 \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*](t \geq 0 \rightarrow \neg \mathcal{U}_\varepsilon(\neg F))$$

$$\overleftrightarrow{\Delta} [x' = f(x)]F \\ \leftrightarrow \forall t \geq 0 \exists \varepsilon > 0 \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*](t \geq 0 \rightarrow \neg \mathcal{U}_\varepsilon(\neg F))$$

### Example ()

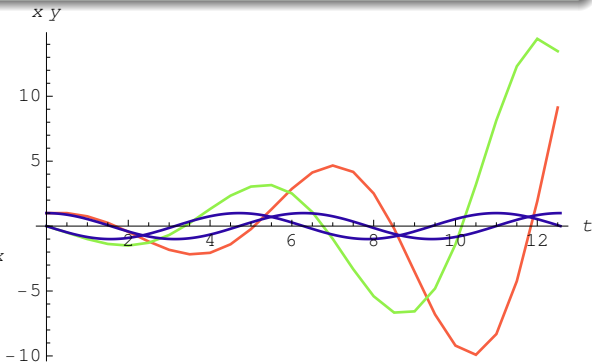
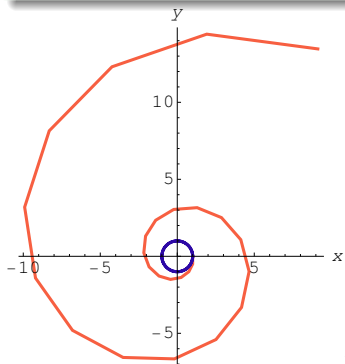
$$\models x^2 + y^2 < 1 \rightarrow [x' = y, y' = -x]x^2 + y^2 < 1.1$$

$$\overleftrightarrow{\Delta} [x' = f(x)]F$$

$$\leftrightarrow \forall t \geq 0 \exists \epsilon > 0 \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*](t \geq 0 \rightarrow \neg \mathcal{U}_\epsilon(\neg F))$$

Example (Incomplete for closed  $F$ )

$$\models x^2 + y^2 \leq 1 \rightarrow [x' = y, y' = -x]x^2 + y^2 \leq 1$$

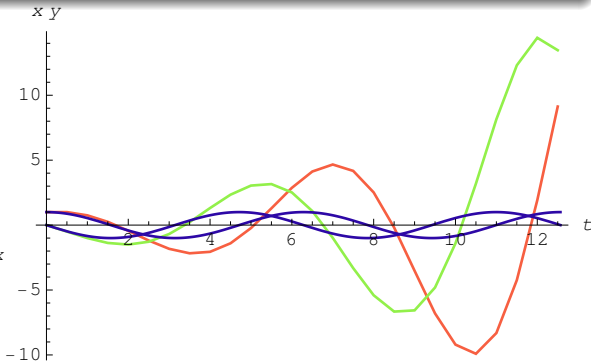
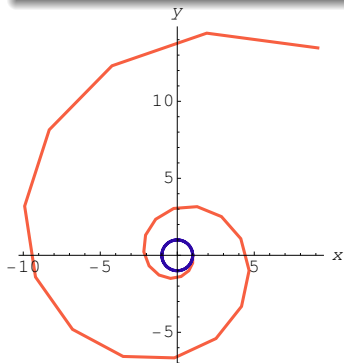


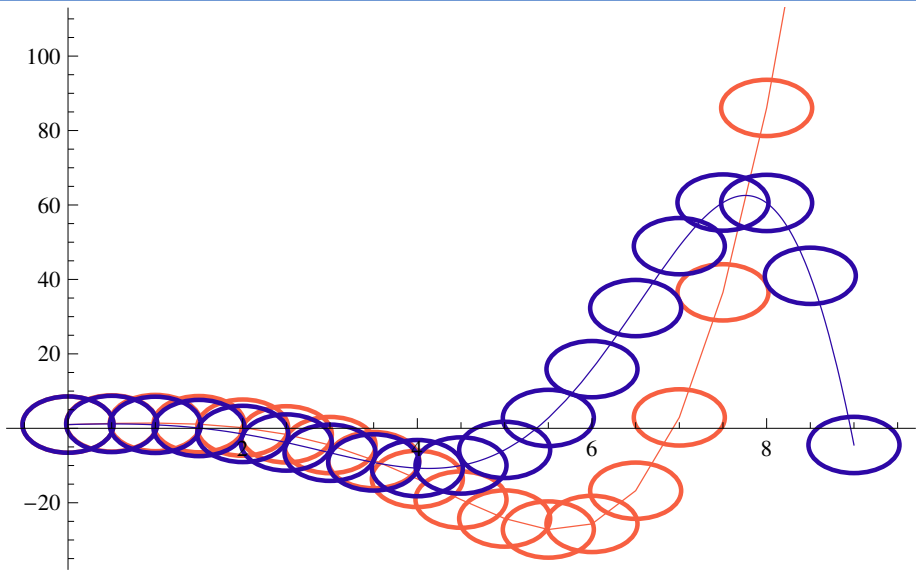
$$\overleftrightarrow{\Delta} [x' = f(x)]F \quad (\text{open})$$

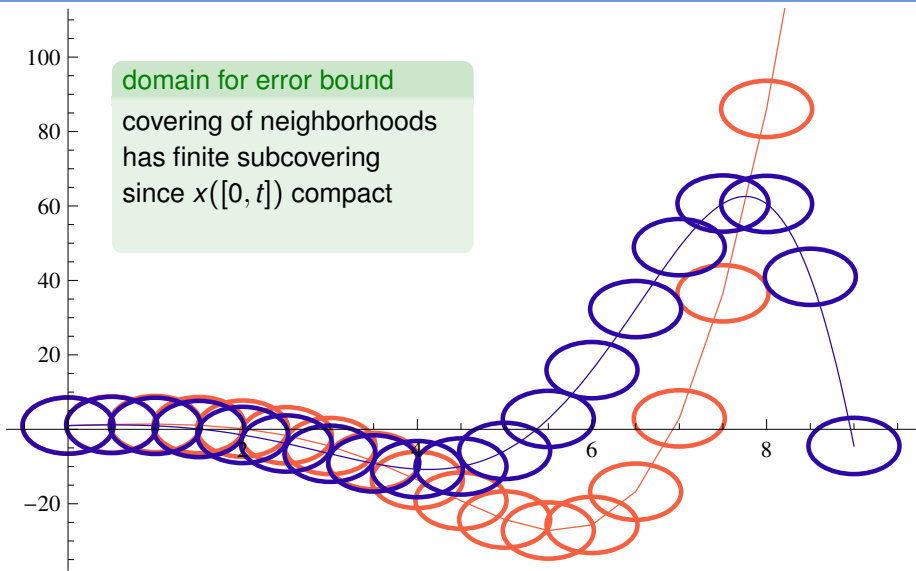
$$\leftrightarrow \forall t \geq 0 \exists \varepsilon > 0 \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*](t \geq 0 \rightarrow \neg \mathcal{U}_\varepsilon(\neg F))$$

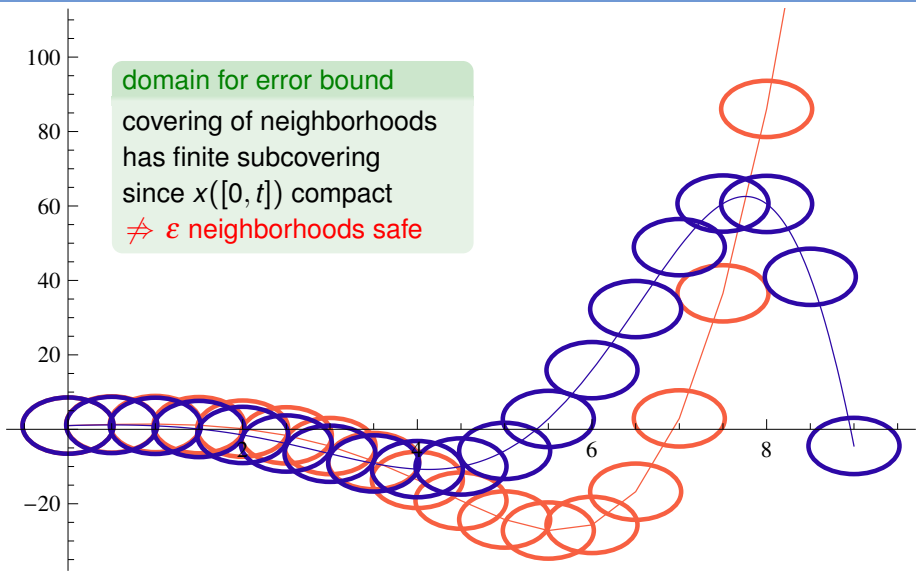
Example (Incomplete for closed  $F$ )

$$\models x^2 + y^2 \leq 1 \rightarrow [x' = y, y' = -x]x^2 + y^2 \leq 1$$











$$\overleftarrow{\Delta} \quad [x' = f(x)]F \leftarrow \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*]F \quad (\text{closed})$$

## Proof Sketch.

- 1  $\omega \models \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*]F$        $\hat{x}^n = x$  at iteration  $n$
- 2  $x \in C^2([0, t])$  solves  $x' = f(x)$  and  $x(0) = \omega$ . NTS  $x(t) \models F$
- 3  $f \in C^1$  locally Lipschitz iff Lipschitz on compact subsets  $\Leftarrow$  loc. compact
- 4 Fix  $E > 0$ . Let  $L$  Lipschitz constant of  $f \in C^1$  on compact image  
 $U \stackrel{\text{def}}{=} \overline{\mathcal{W}}_E(x([0, t])) = \bigcup_{q \in x([0, t])} \overline{\mathcal{W}}_E(q)$  of  $x([0, t]) \times \overline{\mathcal{W}}_E(0)$  under  $+$ .  

$$\|x(nh) - \hat{x}^n\| \leq h \max_{\zeta \in [0, t]} \|x''(\zeta)\| \frac{e^{Lt} - 1}{2L} < \varepsilon < E \quad \text{for small } (h \ll 1)$$

$$\|x(t) - x(nh)\| \stackrel{\text{MVT}}{=} \|x'(\xi)\| (t - nh) \leq \max_{\xi \in [0, t]} \|f(x(\xi))\| (t - nh) < \varepsilon \quad (h \ll 1)$$

$$\|x(t) - \hat{x}^n\| \leq \|x(t) - x(nh)\| + \|x(nh) - \hat{x}^n\| < 2\varepsilon \quad (h \ll 1)$$
- 5 Sequence  $\hat{x}^n \rightarrow x(t)$  as  $h \rightarrow 0$  and  $\hat{x}^n \models F$  closed so  $x(t) \models F$ .       $\square$

$\vec{\Delta} [x' = f(x)]F \rightarrow \forall t \geq 0 \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*](t \geq 0 \rightarrow F)$  (open)

### Proof Sketch.

- 1  $\omega \models [x' = f(x)]F$   $\hat{x}^n = x$  at iteration  $n$
- 2  $x \in C^2([0, t])$  solves  $x' = f(x)$  and  $x(0) = \omega$ . Compact  $x([0, t]) \subseteq F$  open
- 3  $0 < E < \inf_{q \in x([0, t])} d(q, \llbracket F \rrbracket^c)$  has compact  $U \stackrel{\text{def}}{=} \overline{\mathcal{W}}_E(x([0, t]))$  in  $F$ .
- 4 Let  $L$  Lipschitz constant of  $f \in C^1$  on compact  $U$ .

$$\|x(nh) - \hat{x}^n\| \leq h \max_{\zeta \in [0, t]} \|x''(\zeta)\| \frac{e^{Lt} - 1}{2L} < \varepsilon < E \quad \text{for small } (h \ll 1)$$

$$\|x(t) - x(nh)\| \stackrel{\text{MVT}}{=} \|x'(\xi)\|(t-nh) \leq \max_{\xi \in [0, t]} \|f(x(\xi))\|(t-nh) < \varepsilon \quad (h \ll 1)$$

$$\|x(t) - \hat{x}^n\| \leq \|x(t) - x(nh)\| + \|x(nh) - \hat{x}^n\| < 2\varepsilon \quad (h \ll 1)$$

- 5  $\omega \models \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*](t \geq 0 \rightarrow F)$  for  $h \ll 1, nh \leq t$   
as  $\hat{x}^n \models F$  for  $h \ll 1, nh \leq t$  by 4a since  $t \geq 0$  after loop iff  $nh \leq t$  before □

$$[x' = f(x)]F \leftrightarrow \forall t \geq 0 \exists \varepsilon > 0 \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*](t \geq 0 \rightarrow \neg \mathcal{U}_\varepsilon(\neg F))$$

Proof Sketch.

(open).

- 1 “ $\rightarrow$ ”  $\omega \models [x' = f(x)]F$  (“ $\leftarrow$ ” derives from  $\overleftrightarrow{\Delta}$  as  $\neg \mathcal{U}_\varepsilon(\neg F)$  closed)
- 2  $x \in \mathcal{C}^2([0, t])$  solves  $x' = f(x)$  and  $x(0) = \omega$ . Compact  $x([0, t]) \subseteq F$  open
- 3  $0 < E < \inf_{q \in x([0, t])} d(q, \llbracket F \rrbracket^c)$  has compact  $U \stackrel{\text{def}}{=} \overline{\mathcal{U}}_E(x([0, t]))$  in  $F$ .
- 4  $\omega \models [x' = f(x)](t \geq 0 \rightarrow \forall z (\|z - x\| < E \rightarrow F(z)))$  by (3)

$$\|x(nh) - \hat{x}^n\| \leq h \max_{\zeta \in [0, t]} \|x''(\zeta)\| \frac{e^{Lt} - 1}{2L} < \varepsilon < E \quad \text{for small } (h \ll 1)$$

$$\|x(t) - x(nh)\| \stackrel{\text{MVT}}{=} \|x'(\xi)\|(t - nh) \leq \max_{\xi \in [0, t]} \|f(x(\xi))\|(t - nh) < \varepsilon \quad (h \ll 1)$$

$$\|x(t) - \hat{x}^n\| \leq \|x(t) - x(nh)\| + \|x(nh) - \hat{x}^n\| < 2\varepsilon \quad (h \ll 1)$$

- 5  $\|x(nh) - z\| \leq \|x(nh) - \hat{x}^n\| + \|\hat{x}^n - z\| < 2\varepsilon \leq E$  for  $h \ll 1$ ,  $\|\hat{x}^n - z\| < \varepsilon$ .
- 6  $F(z)$  true at these  $z$  by (4).
- 7  $n$ th iterate  $\omega_n \models t \geq 0 \rightarrow \underbrace{\forall z (\|z - x\| < \varepsilon \rightarrow F(z))}_{\neg \mathcal{U}_\varepsilon(\neg F)}$  as  $\omega_n \models t \geq 0$  iff  $\omega \models nh \leq t$

$\neg \mathcal{U}_\varepsilon(\neg F)$



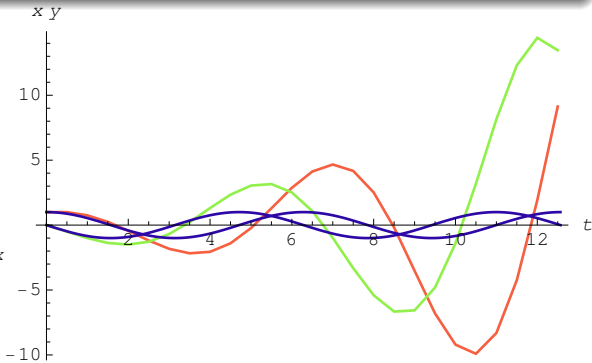
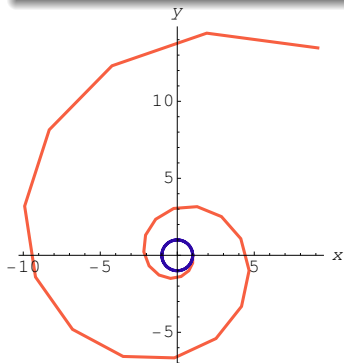
$\Leftrightarrow$   
 $\Delta$  axiom for open  $F$ , but  $F$  may be closed

$$\overleftrightarrow{\Delta} [x' = f(x)]F \quad (\text{open})$$

$$\leftrightarrow \forall t \geq 0 \exists \epsilon > 0 \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*](t \geq 0 \rightarrow \neg \mathcal{U}_\epsilon(\neg F))$$

Example (Incomplete for closed  $F$ )

$$\models x^2 + y^2 \leq 1 \rightarrow [x' = y, y' = -x]x^2 + y^2 \leq 1$$



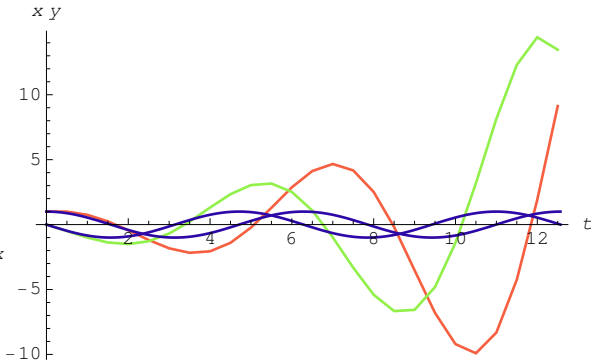
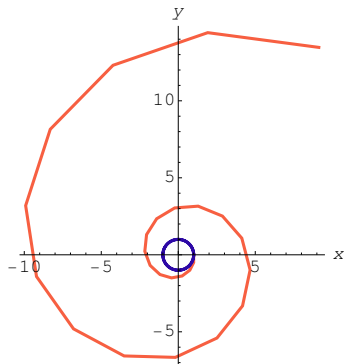
$$\dot{U} \quad [x' = f(x)]F \leftrightarrow \forall \epsilon > 0 [x' = f(x)] \mathcal{U}_\epsilon(F)$$

( $\Leftarrow$  B,V,G,K)

$$\dot{U} \quad [x' = f(x)]F \leftrightarrow \forall \epsilon > 0 [x' = f(x)] \mathcal{U}_\epsilon(F) \quad (\Leftarrow B, V, G, K)$$

Example (Closed  $\rightsquigarrow$  Quantified Open)

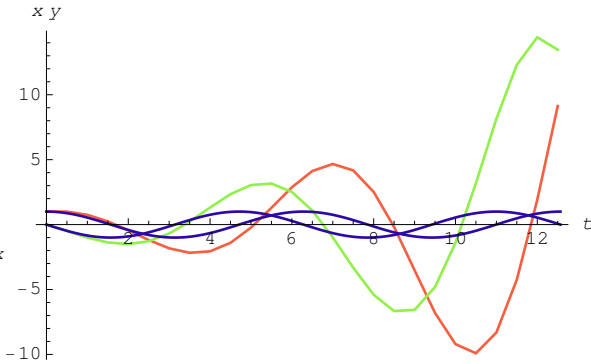
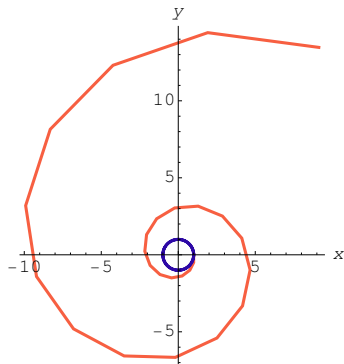
$$\models x^2 + y^2 \leq 1 \rightarrow [x' = y, y' = -x] x^2 + y^2 \leq 1$$



$$\dot{U} \quad [x' = f(x)]F \leftrightarrow \forall \epsilon > 0 [x' = f(x)] \mathcal{U}_\epsilon(F) \quad (\Leftarrow B, V, G, K)$$

Example (Closed  $\rightsquigarrow$  Quantified Open)

$$\models x^2 + y^2 \leq 1 \rightarrow [x' = y, y' = -x] \forall \epsilon > 0 x^2 + y^2 < 1 + \epsilon$$

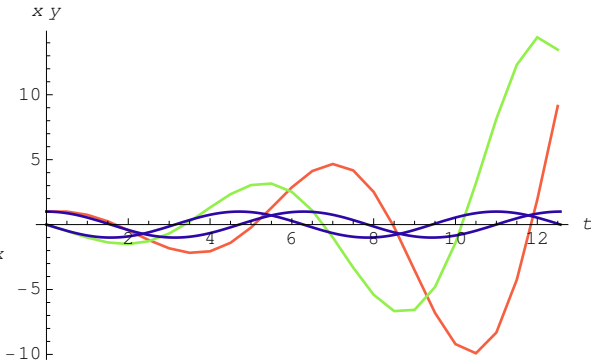
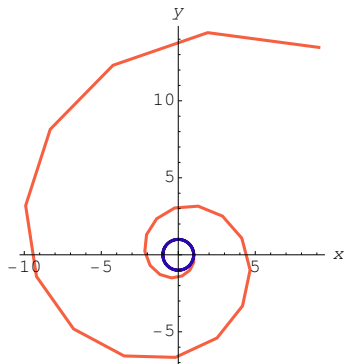




$$\dot{U} \quad [x' = f(x)]F \leftrightarrow \forall \epsilon > 0 [x' = f(x)] \mathcal{U}_\epsilon(F) \quad (\Leftarrow \text{B,V,G,K})$$

Example (Closed  $\rightsquigarrow$  Quantified Open)

$$\models x^2 + y^2 \leq 1 \rightarrow \forall \epsilon > 0 [x' = y, y' = -x] x^2 + y^2 < 1 + \epsilon$$



$\Leftrightarrow$   
 $\Delta$  axiom for open/closed  $F$ , but otherwise?

Example (Locally Closed  $\rightsquigarrow$  Open, Closed)

$$\models O \wedge C \rightarrow [x' = y, y' = -x](O \wedge C)$$

$$\Box \wedge [\alpha](O \wedge C) \leftrightarrow [\alpha]O \wedge [\alpha]C$$

( $\Leftarrow$  K)

Example (Locally Closed  $\rightsquigarrow$  Open, Closed)

$$\models O \wedge C \rightarrow [x' = y, y' = -x](O \wedge C)$$

$$\Box \wedge [\alpha](O \wedge C) \leftrightarrow [\alpha]O \wedge [\alpha]C \quad (\Leftarrow K)$$

Example (Locally Closed  $\rightsquigarrow$  Open, Closed)

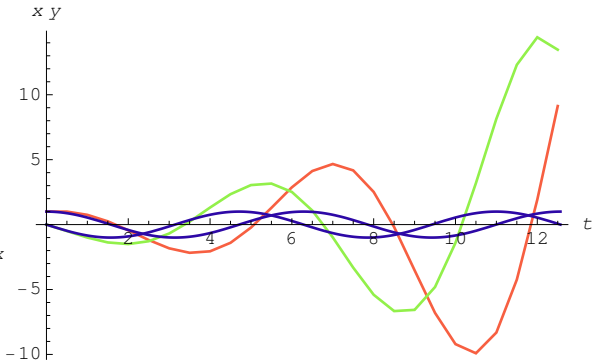
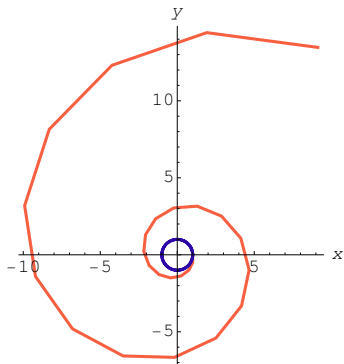
$$\models O \wedge C \rightarrow [x' = y, y' = -x]O \wedge [x' = y, y' = -x]C$$

$$\check{U} \quad [x' = f(x)](O \vee C) \leftrightarrow \forall \check{\epsilon} > 0 [x' = f(x)](O \vee \mathcal{U}_{\check{\epsilon}}(C)) \quad (\Leftarrow \text{B,V,G,K})$$

$$\checkmark [x' = f(x)](O \vee C) \leftrightarrow \forall \epsilon > 0 [x' = f(x)](O \vee \mathcal{U}_\epsilon(C)) \quad (\Leftarrow B, V, G, K)$$

Example ((Open  $\vee$  Closed)  $\rightsquigarrow$  Quantified Open)

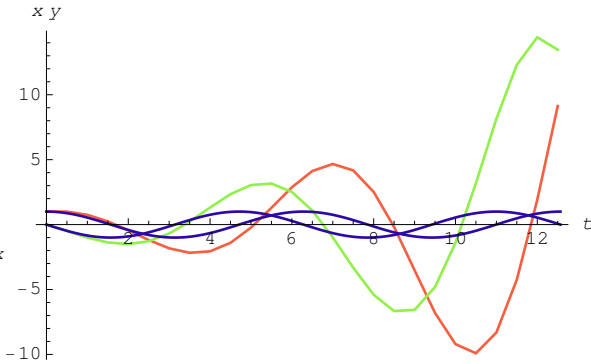
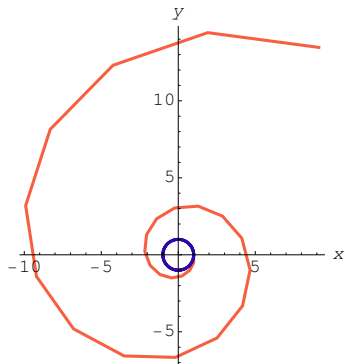
$$\models O \vee C \rightarrow [x' = y, y' = -x](O \vee C)$$



$$\checkmark [x' = f(x)](O \vee C) \leftrightarrow \forall \epsilon > 0 [x' = f(x)](O \vee \mathcal{U}_\epsilon(C)) \quad (\Leftarrow \text{B,V,G,K})$$

Example ((Open  $\vee$  Closed)  $\rightsquigarrow$  Quantified Open)

$$\models O \vee C \rightarrow [x' = y, y' = -x](O \vee \forall \epsilon > 0 \mathcal{U}_\epsilon(C))$$

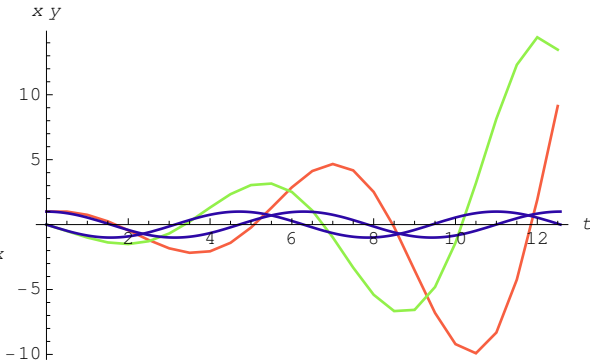
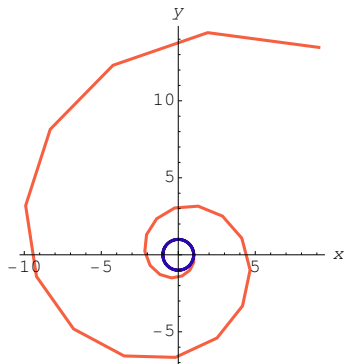




$$\checkmark [x' = f(x)](O \vee C) \leftrightarrow \forall \epsilon > 0 [x' = f(x)](O \vee \mathcal{U}_\epsilon(C)) \quad (\Leftarrow B, V, G, K)$$

Example ((Open  $\vee$  Closed)  $\rightsquigarrow$  Quantified Open)

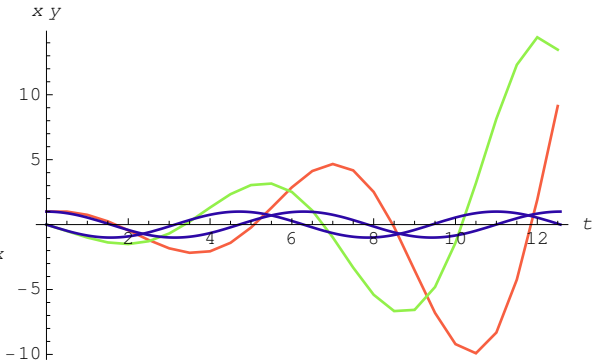
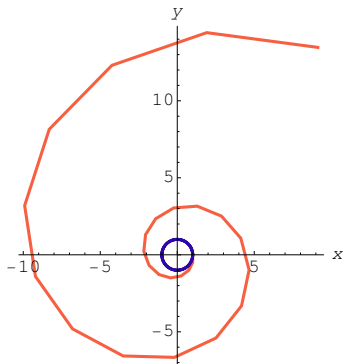
$$\models O \vee C \rightarrow [x' = y, y' = -x] \forall \epsilon > 0 (O \vee \mathcal{U}_\epsilon(C))$$



$$\checkmark [x' = f(x)](O \vee C) \leftrightarrow \forall \epsilon > 0 [x' = f(x)](O \vee \mathcal{U}_\epsilon(C)) \quad (\Leftarrow B, V, G, K)$$

Example ((Open  $\vee$  Closed)  $\rightsquigarrow$  Quantified Open)

$$\models O \vee C \rightarrow \forall \epsilon > 0 [x' = y, y' = -x](O \vee \mathcal{U}_\epsilon(C))$$



$\Delta$  axiom for semialgebraic  $F$ , but otherwise?

Theorem (Relative Completeness / Continuous) (JAR'08,LICS'12)

dL calculus is a sound & complete axiomatization of hybrid systems relative to *differential equations*.  
 $\models \varphi$  implies  $\text{Taut}_{\text{FOD}} \vdash \varphi$

Theorem (Relative Completeness / Discrete) (LICS'12)

dL calculus +  $\overleftrightarrow{\Delta}$  is a sound & complete axiomatization of hybrid systems relative to *discrete dynamics*.  
 $\models \varphi$  implies  $\text{Taut}_{\text{DL}} \vdash \varphi$

Proof.

- 1 dL/ODE complete  $\Rightarrow$  suffices  $\models \varphi$  implies  $\text{Taut}_{\text{DL}} \vdash \varphi$  for  $\varphi \in \text{FOD}$
- 2  $[x' = f(x)]F$  for first-order  $F$  see previous slides.
- 3 propositional connectives and quantifiers see schematic completeness.
- 4  $\vdash_{\text{DL}} \langle x' = f(x) \rangle F \leftrightarrow (\langle x' = f(x) \rangle F)^b$  see previous slides.  $\square$

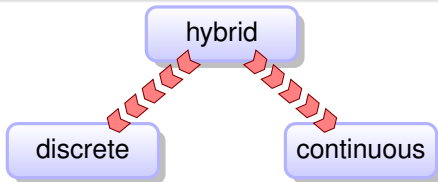
## Theorem (Equi-expressibility)

(LICS'12)

dL (constructively) expressible in FOD and in DL:

$$\forall \varphi \exists \varphi^b \in \text{FOD} \models \varphi \leftrightarrow \varphi^b$$

$$\forall \varphi \exists \varphi^\# \in \text{DL} \models \varphi \leftrightarrow \varphi^\#$$



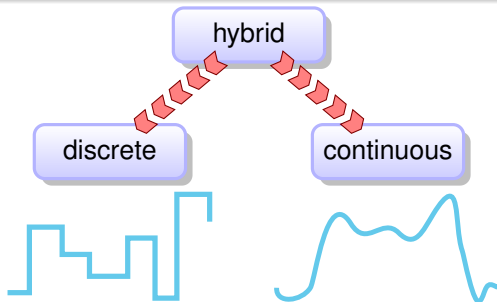
## Theorem (Equi-expressibility)

(LICS'12)

dL (constructively) expressible in FOD and in DL:

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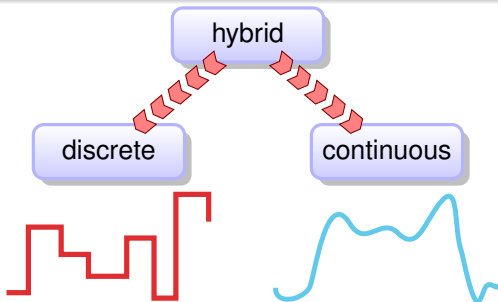
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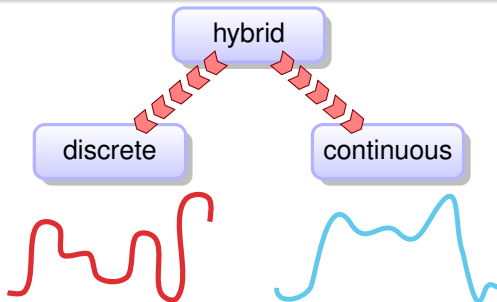
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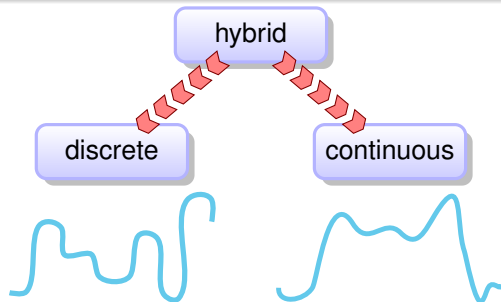
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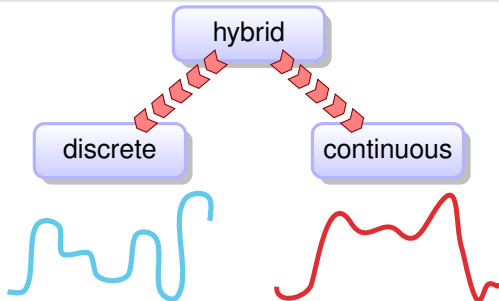
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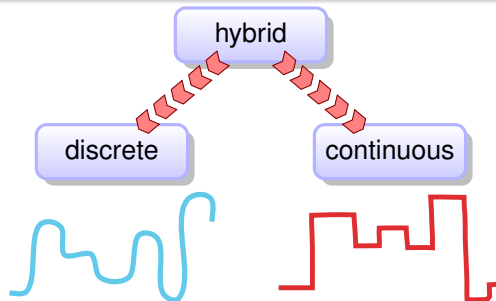
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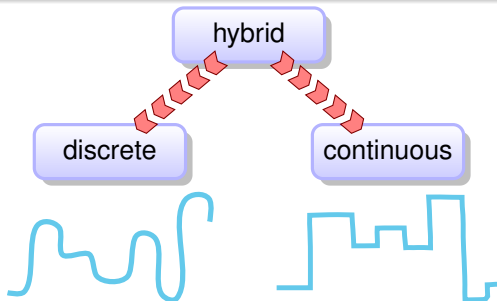
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## Theorem (Relative Decidability)

(LICS'12)

*Validity of dL sentences is decidable relative to FOD or relative to DL.*

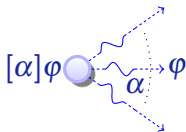
## Proof.

- 1 Let  $\varphi$  a sentence in dL ( $FV(\varphi) = \emptyset$ ) and  $\omega$  a state.
- 2 Either  $\omega \models \varphi$  or  $\omega \not\models \varphi$ . So either  $\omega \models \varphi$  or  $\omega \models \neg\varphi$ .
- 3 By coincidence,  $\omega \models \varphi$  iff  $v \models \varphi$  for arbitrary  $v$ , as  $FV(\varphi)$ , no symbols.
- 4 Either  $\models \varphi$  or  $\models \neg\varphi$ .
- 5 Either  $\vdash_L \varphi$  or  $\vdash_L \neg\varphi$  by completeness relative to  $L = \text{FOD}$ ,  $L = \text{DL}$ .  $\square$

- 1 Hybrid Systems
- 2 Differential Dynamic Logic
  - Syntax
  - Semantics
  - Axiomatization
- 3 Continuous Completeness
  - Schematic Completeness
  - Expressibility and Rendition of Hybrid Programs
- 4 Discrete Completeness
  - Open Discrete Completeness
  - Closed Discrete Completeness
  - Semialgebraic Discrete Completeness of  $dL + \Delta$
  - Discrete Completeness of  $dL + \Delta$
  - Equi-expressible
  - Relative Decidable
- 5 Summary

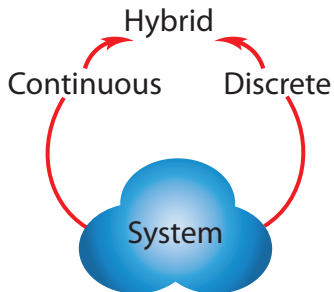
differential dynamic logic

$$dL = DL + HP$$



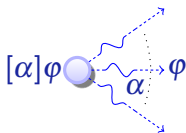
proof-theoretical alignment

continuous = hybrid = discrete



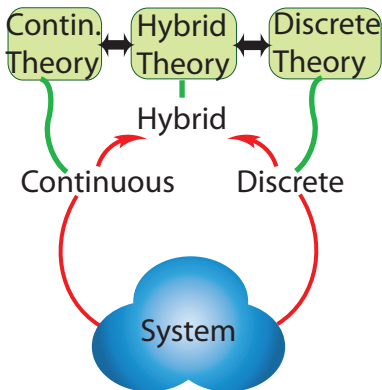
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