

Non-Standard Semantics for Differential Dynamic Logic

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Proving Properties of Differential Equations

1. Discretize:

$$[x' = f(x)]F \leftrightarrow \forall t \geq 0 \exists \varepsilon < 0 \exists h_0 > 0 \forall 0 < h < h_0 [(x := x + hf(x))^*](t \geq 0 \rightarrow \neg U_\varepsilon(\neg F))$$

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2. Average:

$$\models x > 0 \rightarrow [x' = f(x)]x > 0 \quad \Leftarrow \quad \models x > 0 \rightarrow f(x) > 0$$

The hyperreals

Theorem (A. Robinson)

There is an extension \mathbb{R}^ of \mathbb{R} as ordered fields containing an infinitesimal ε .*

Expanding $d\mathcal{L}$

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The syntax for $d\mathcal{L}^*$ is the syntax for $d\mathcal{L}$ with an additional constant symbol ε and a unary function symbol $\hat{\cdot}$:

Terms: $e ::= x \mid x' \mid c \mid e + \tilde{e} \mid e - \tilde{e} \mid e \cdot \tilde{e} \mid e / \tilde{e} \mid q \mid \varepsilon \mid \hat{e}$

Formulas: $P, Q ::= e \geq \tilde{e} \mid \neg P \mid P \wedge Q \mid \exists x P \mid [\alpha] P$

Programs: $\alpha, \beta ::= x := e \mid ?Q \mid x' = f(x) \ \& \ Q \mid \alpha \cup \beta \mid \alpha; \beta \mid \alpha^*$

Semantics for $d\mathcal{L}^*$

Definition

Let \mathcal{V} be the set of variables. A hyperstate is a map $\omega : \mathcal{V} \rightarrow \mathbb{R}^*$.
Write \mathcal{S}^* for the set of hyperstates.

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▶ $\omega_*[[\varepsilon]] = \varepsilon$

▶ $\omega_*[[\hat{e}]] = \hat{e}$

Write \models_* for those semantics.

Definition (Semantics of ODE programs)

For a continuous program $(\omega, \nu) \in \llbracket x' = f(x) \ \& \ Q \rrbracket_*$ exactly if there is $r \in \mathbb{R}^*$ finite and a map

$$\varphi : [0, r]^* \rightarrow \mathcal{S}^*, \quad t \mapsto \varphi_t$$

such that $\varphi_0 = \omega$ except at x' , $\varphi_r = \nu$ and $\varphi \models_* x' = f(x) \ \& \ Q$.

Here $\varphi \models_* x' = f(x) \ \& \ Q$ abbreviates the statement that

$\varphi_z(y) = \varphi_0(y)$ for all $y \in \mathcal{V} \setminus \{x, x'\}$ whenever $z \in [0, r]^*$ and for all $n \in \mathbb{N}^*$ with $n \cdot \varepsilon \leq r$:

1. $\varphi_{n \cdot \varepsilon}(x) = W^n(\varphi_0(x))$, where W^n is the hyperreal walk,
2. $z \mapsto \varphi_z(x)$ is constant on $[n \cdot \varepsilon, (n+1) \cdot \varepsilon)^*$ and
3. $\varphi_{n \cdot \varepsilon} \in \llbracket x' = f(x) \ \& \ Q \rrbracket_*$.

Transfer principle

Theorem (ODE Transfer Principle)

For \mathcal{L} -formulas $p(x)$, $q(x)$ and a standard state $\omega \in \mathcal{S}$. Equivalent are

- ▶ $\omega \models [x' = f(x) \ \& \ q(x)]p(x)$
- ▶ $\omega \models_* [x' = f(x) \ \& \ q(\hat{x}) \wedge \text{fin}(x)]p(\hat{x})$

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- ▶ Base: sequent calculus
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- ▶ \vdash_* contains the axiom $[:=]$ and the proof rules G and $M[\cdot]$

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The axioms DG and DC are also sound for \vdash_* .

A Differential Invariant Proof Rule

We can add another sound proof rule DI^* to \vdash_* to get:

Theorem

For a modality free $d\mathcal{L}$ -formula $p(x)$ the following are equivalent

1. $\vdash_* p(x) \rightarrow [x' = f(x) \ \& \ q(x)]p(x)$
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Example

Proving $x > 0 \rightarrow [x' = -x]x > 0$ is equivalent to proving $x > 0 \rightarrow x - \varepsilon x > 0$.

Proving more differential invariants

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Small errors stay small:

Theorem

For any $m > 1$ and any hat-free term g the axiom

$$\rho \approx 0 \wedge \text{fin}(g) \rightarrow [\rho' = g \cdot \varepsilon^m] \rho \approx 0$$

is sound for \models_ .*

Question: Can every differential invariant, including those containing hats, be proved in (a modification of) \vdash_* .