

Nondeterministic Discrete Stochastic Differential Dynamic Logic

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December 10, 2019

$$\frac{\sigma(\rho(\alpha, P), p) \overset{d\mathcal{L}}{\rightsquigarrow} Q}{\langle\!\langle\alpha\rangle\!\rangle P \leq p \overset{d\mathcal{L}}{\rightsquigarrow} Q} \text{ (d}\mathcal{L}\text{-}\langle\!\langle\rangle\!\rangle)$$

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- Problem: no implementations!

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Term $e_1, e_2 ::= x \mid c \mid e_1 + e_2 \mid e_1 \cdot e_2$

Formula $P, Q ::= e_1 \geq e_2 \mid e_1 = e_2 \mid \neg P \mid P \odot Q \mid \forall x P \mid \exists x P \mid [\alpha]P \mid \langle \alpha \rangle P$
 $\mid \langle \alpha \rangle P \leq p$ ($\odot \in \{\wedge, \vee, \rightarrow, \leftrightarrow\}$)

Program $\alpha, \beta ::= x := e \mid x := * \mid x := \{p_1 : e_1, \dots, p_n : e_n\} \mid ?P \mid \alpha; \beta$
 $\mid \alpha^* \mid \alpha^{*:P} \mid \alpha \cup \beta \mid \bigoplus_{i=1}^n p_i \alpha_i \mid x' = f(x) \ \& \ P$

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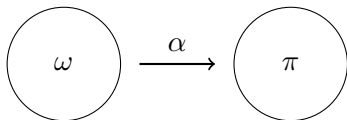
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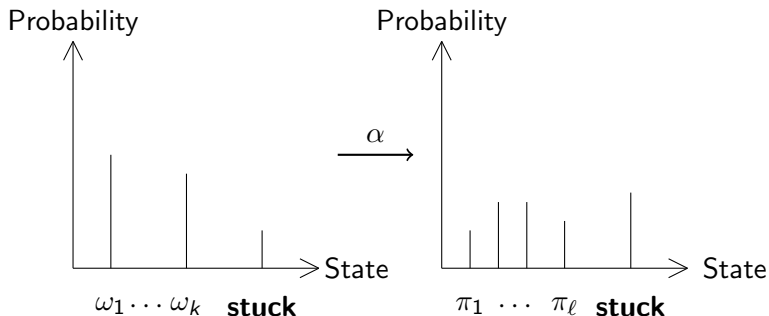
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- $\alpha^{*:P}$: Probabilistic loop
- $\bigoplus_{i=1}^n p_i \alpha_i$: Probabilistic choice

- $d\mathcal{L}$: transition between states

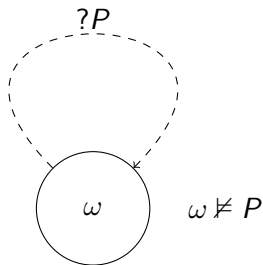


Program Semantics

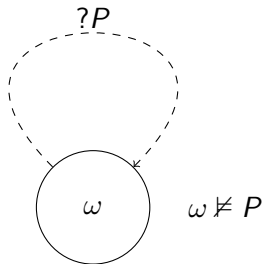
- $d\mathcal{L}$: transition between states
- $\text{NDSd}\mathcal{L}$: transition between **probability distributions of states**



- $d\mathcal{L}$: Failed test: no transition



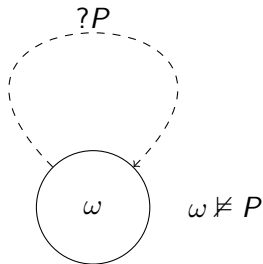
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- $NDSd\mathcal{L}$: Failed test: mapped to **stuck**

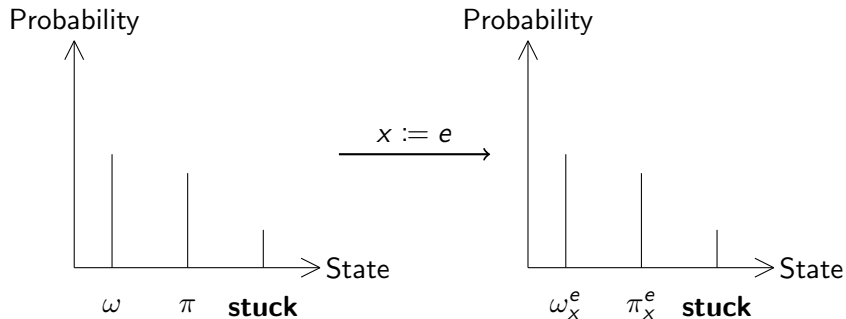
stuck?

- $d\mathcal{L}$: Failed test: no transition

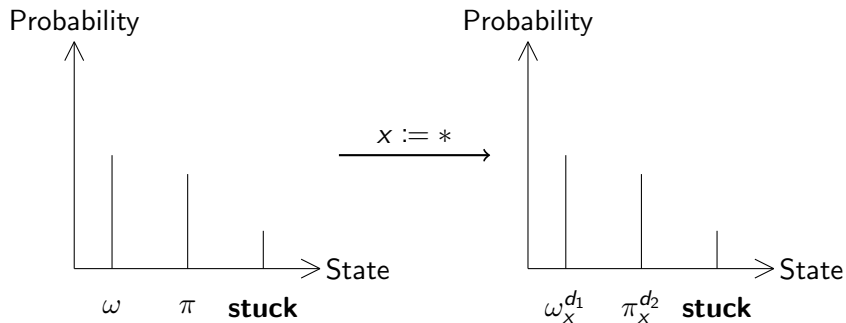


- NDSd \mathcal{L} : Failed test: mapped to **stuck**
- **stuck** is not a state!

Program Semantics: Assignment

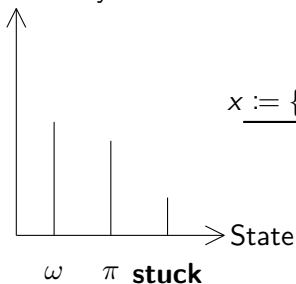


Program Semantics: Nondeterministic Assignment



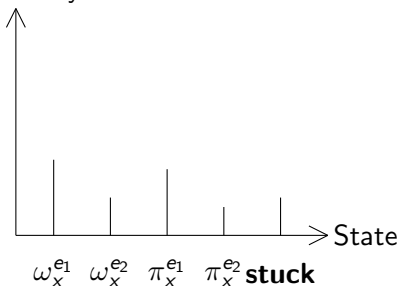
Program Semantics: Probabilistic Assignment

Probability

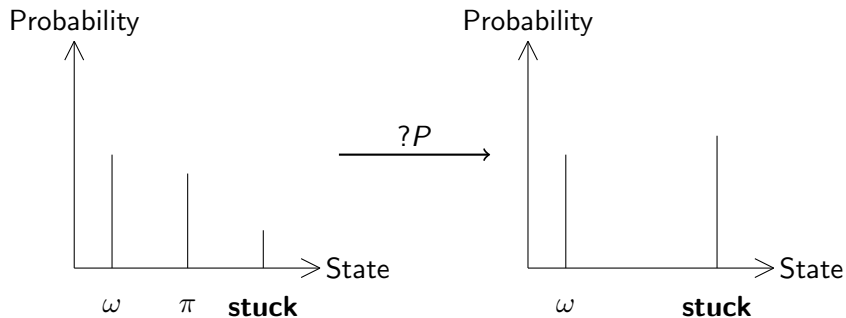


$$\underline{x := \{p_1 : e_1, p_2 : e_2\}}$$

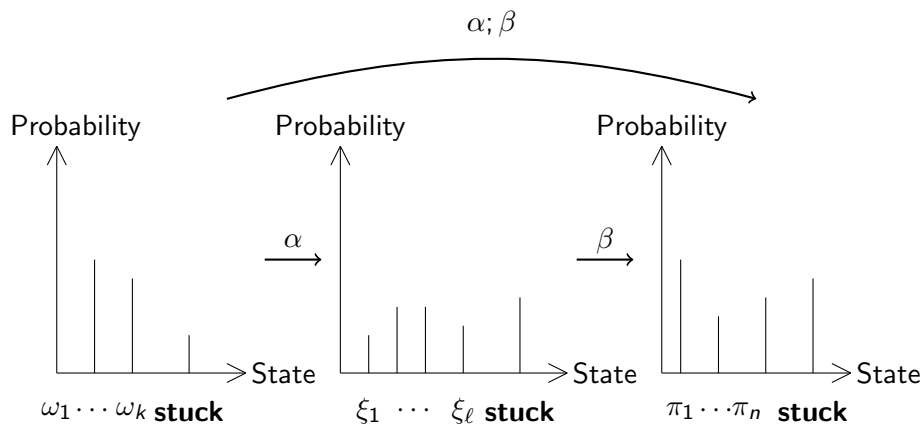
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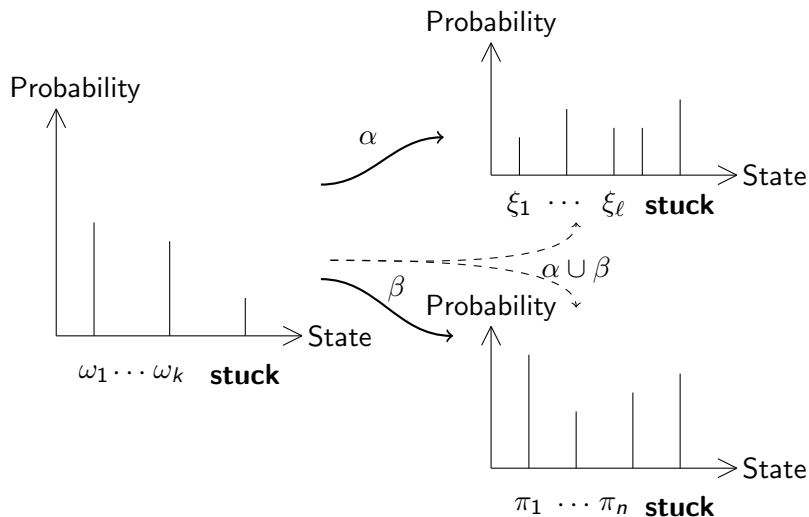
Program Semantics: Test



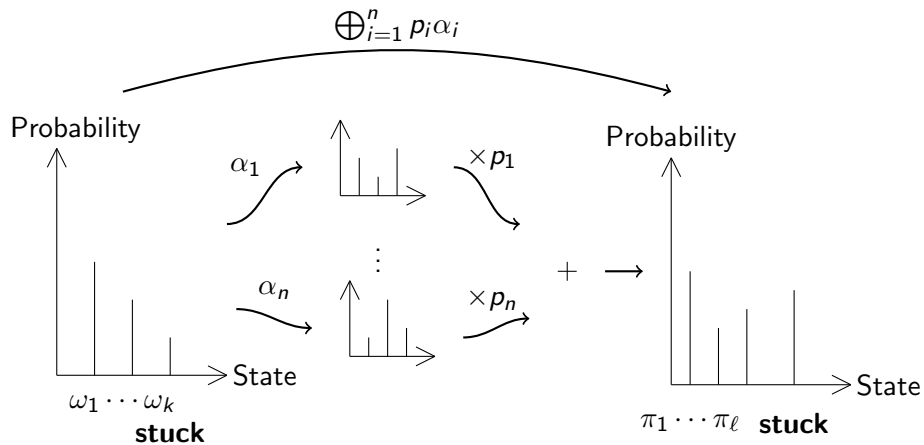
Program Semantics: Sequential Composition



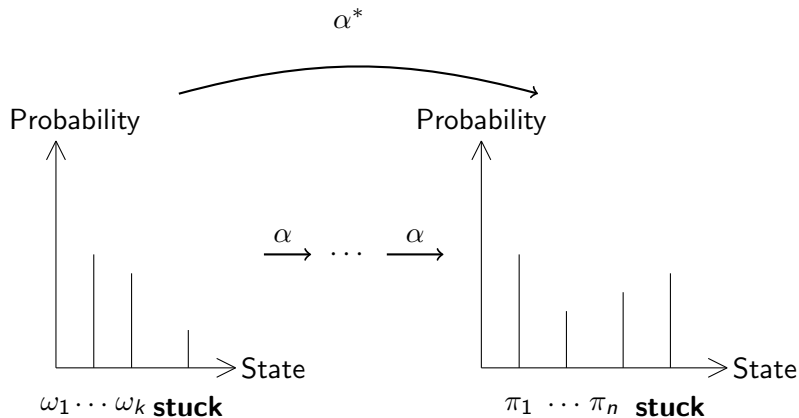
Program Semantics: Nondeterministic Choice



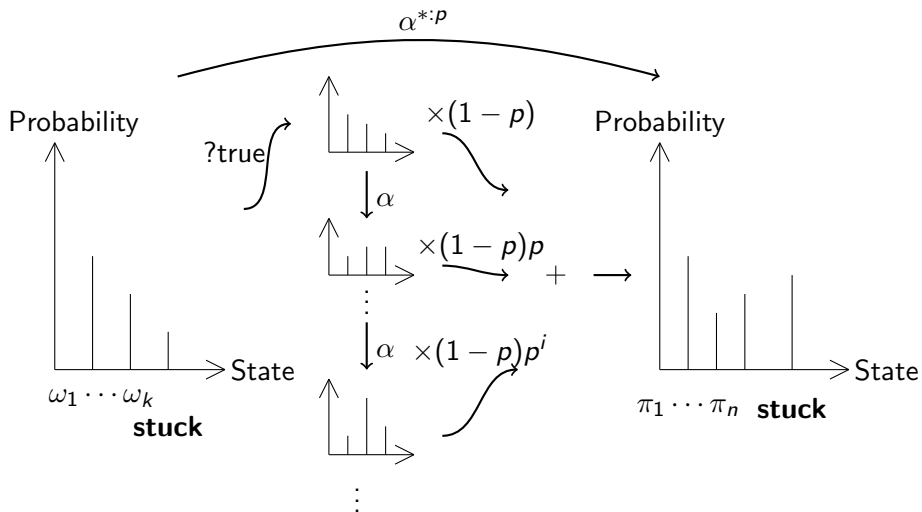
Program Semantics: Probabilistic Choice



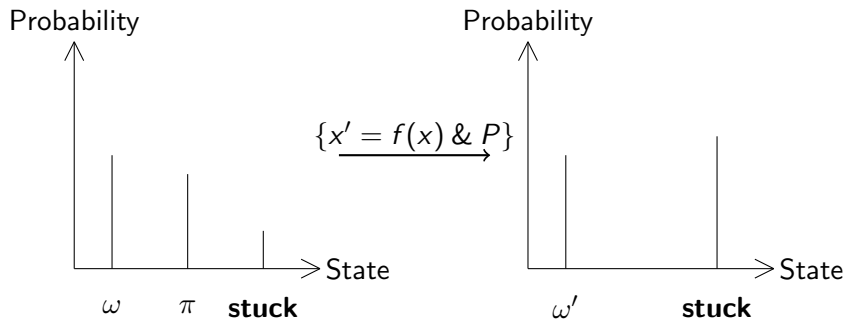
Program Semantics: Nondeterministic Loop



Program Semantics: Probabilistic Loop



Program Semantics: ODE



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- Probability bound:

$$\omega \in \llbracket \langle \alpha \rangle P \leq p \rrbracket \text{ iff } \omega \in \llbracket \sigma(\rho(\alpha, P), p) \rrbracket$$

$$\sigma(\rho(\alpha, P), \rho)$$

- \mathcal{I} : indicator

$$\mathcal{I}(P, y) \equiv (P \wedge (y = 1)) \vee (\neg P \wedge (y = 0))$$

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- σ : finalize ρ

$$\sigma(\left(\{P_1, \dots, P_n\}, e\right), \rho) \equiv \left(\bigwedge_{i=1}^n P_i\right) \rightarrow (e \leq \rho)$$

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$$\rho(\beta; \alpha, P) = \rho(\beta, \langle \alpha \rangle P)$$

Loop Probability Bounds

$$\rho(\beta; \alpha^*, P) = \left(\bigcup_{i=0}^{\infty} X_i, \sup_i e_i \right) \text{ where } (X_i, e_i) = \rho(\beta; \alpha^i, P) \text{ for } i \in \mathbb{N}$$

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Theorem (Probabilistic loop unrolling)

$$\llbracket \alpha^{*:P} \rrbracket = \llbracket (1 - p)\{?true\} \oplus p\{\alpha; \alpha^{*:P}\} \rrbracket$$

Translation to $d\mathcal{L}$: Formulas

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$$\frac{\alpha \xrightarrow{d\mathcal{L}} \bar{\alpha} \quad P \xrightarrow{d\mathcal{L}} \bar{P}}{[\alpha]P \xrightarrow{d\mathcal{L}} [\bar{\alpha}]\bar{P}} \quad (d\mathcal{L}\text{-}[])$$

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$$\frac{\forall 1 \leq i \leq n, \alpha_i \xrightarrow{d\mathcal{L}} \bar{\alpha}_i}{\bigoplus_{i=1}^n p_i \alpha_i \xrightarrow{d\mathcal{L}} \bigcup_{\substack{i=1 \\ p_i \neq 0}}^n \bar{\alpha}_i} \quad (\text{d}\mathcal{L}\text{-}\oplus)$$

Theorem (Soundness of Translation)

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If $\omega \models \langle \alpha \rangle P \leq p$ then $\forall (\text{Det}(\omega), \nu) \in \llbracket \alpha \rrbracket$, $\mathbf{P}[\pi \models P] \leq p$ for $\pi \sim \nu$.

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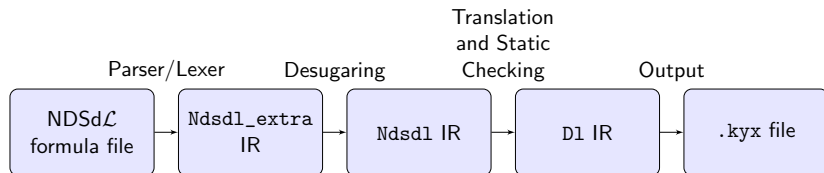
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Theorem (Conservative Extension)

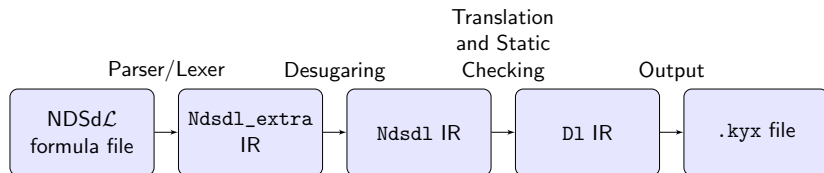
Every valid $\text{d}\mathcal{L}$ formula is also a valid $\text{NDSd}\mathcal{L}$ formula.

- ~850 lines of OCaml

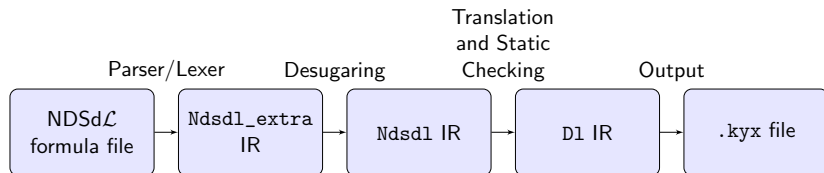


Compiler

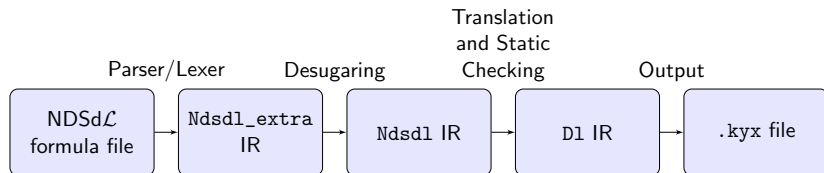
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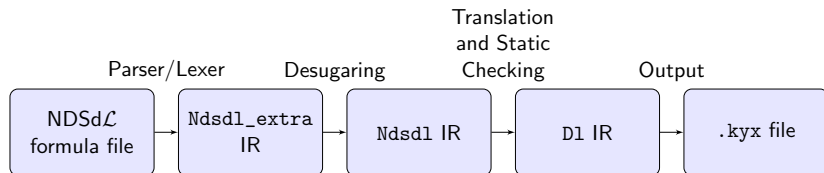
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 - $\{a\}^* @ \text{unroll}(n), \{a\}^*:p @ \text{unroll}(n),$
 $x := \text{Geometric}(p) @ \text{unroll}(n)$



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- Geometric distribution with success probability $3/4$

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Not valid!

$$\langle | x := \text{Geometric}(3/4) @ \text{unroll}(2) \mid \rangle (x \geq 3) \leq 1/16$$

Example (translated)

ProgramVariables

```
Real tt_0;  
Real tt_1;  
Real tt_2;  
Real x;
```

End.

Problem

```
(((((true) & (((<x := 1;>(<?true;>((x) >= (3)))) & ((tt_0) = (1))) | ((!(<x :=  
1;>(<?true;>((x) >= (3)))) & ((tt_0) = (0)))) & (((<x := 1;>(<x := (x)  
+(1);>(<?true;>((x) >= (3)))) & ((tt_1) = (1))) | ((!(<x := 1;>(<x := (x)  
+(1);>(<?true;>((x) >= (3)))) & ((tt_1) = (0)))) & (((<x := 1;>(<x := (x)  
+(1);>(<x := (x)+1;>(<{x := (x)+1;}*>((x) >= (3)))) & ((tt_2) =  
(1))) | ((!(<x := 1;>(<x := (x)+1;>(<x := (x)+1;>(<{x := (x)+1;}*>((x)  
>= (3)))))) & ((tt_2) = (0)))) -> (((((0)+(((1)-((1)-((3)/(4))))*(tt_0  
)))+(((1)-((3)/(4)))*(((0)+(((1)-((1)-((3)/(4))))*(tt_1)))+(((1)-((3)/(4))  
)*(tt_2)))))) <= ((1)/(16)))
```

End.

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- Compiler implementation
- Future work: continuous probability distributions

Questions?

$$\frac{\sigma(\rho(\alpha, P), p) \overset{d\mathcal{L}}{\rightsquigarrow} Q}{\langle \alpha \rangle P \leq p \overset{d\mathcal{L}}{\rightsquigarrow} Q} \quad (\text{d}\mathcal{L}\text{-}\langle \rangle)$$