



Versatile CPS For Data Center Cooling

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Outline

- Motivation
- Approach
 - Two-Aisle Model
 - Physics Model
 - Key Properties
- Results
- Future work
- Conclusion

Motivation

As we need more computing powers, optimizing energy usage and efficiency is very important.

When the safety of the equipment and operation is paramount, it's good to have a formal proof for its safety.



Motivation, Related Works

Optimizing cost based on current electricity cost [Wang 2014]

Change air intake source to achieve optimal cooling efficiency. [Mansousakis 2016]

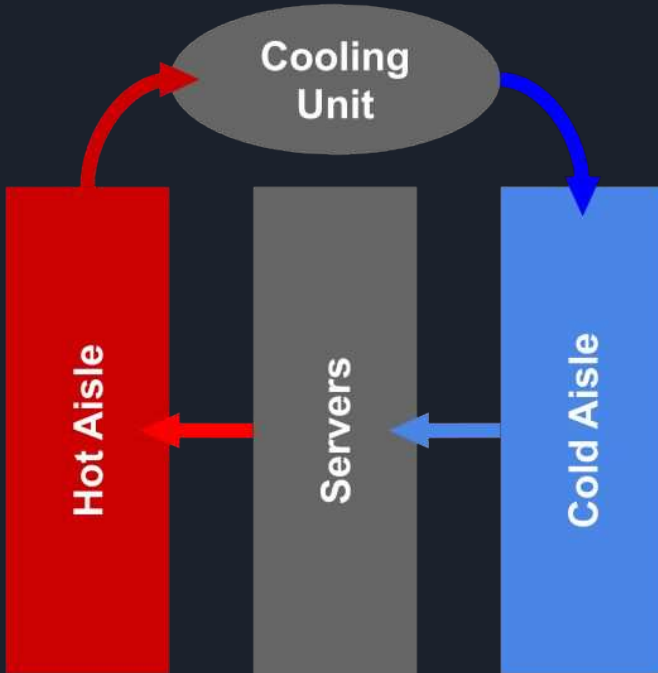
Use neural network frame to predict power usage effectiveness and optimizing cooling base [Yao 2016]

Motivation, Related Works

Distinct things that we want to focus:

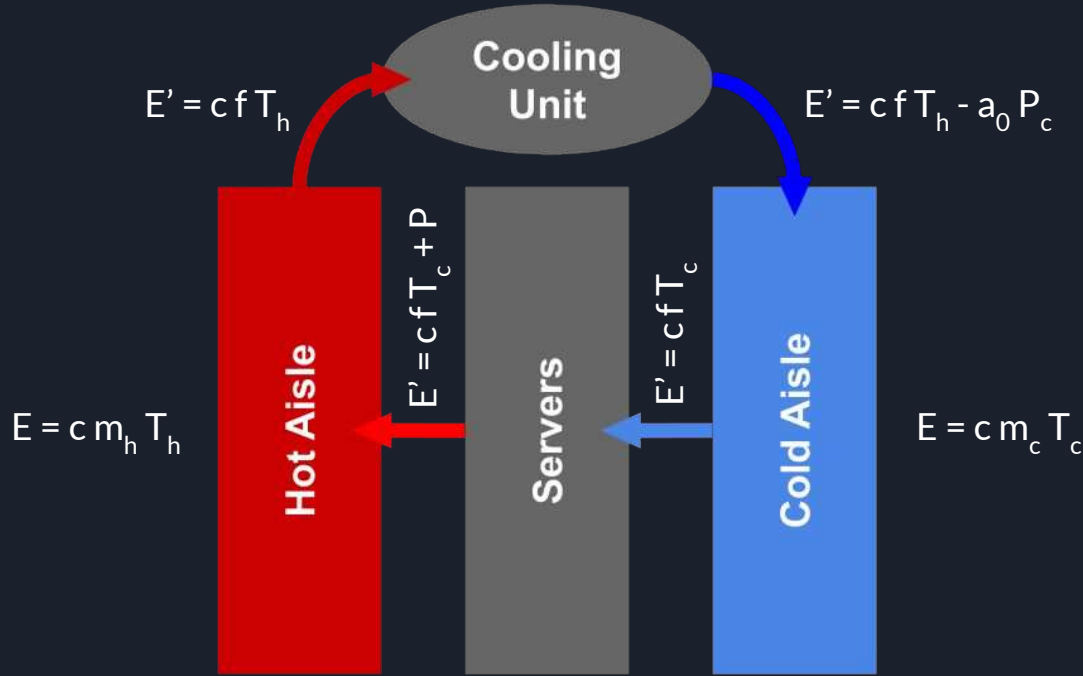
- Hybrid system modeling the temperature and energy in cooling system.
- Formal differential dynamic logic proof of safety of operation.
- Runtime safety system that could be used in conjunction with a wide-variety of "optimized" controllers.

Two-Aisle Model



- Thermal energy inside the datacenter
 - Enters at servers
 - Removed at cooling unit
- Aisles account for all of the thermal mass
- Circulating air moves energy through system
- Controller controls power usage of cooling unit and air circulation speed

Physics Model



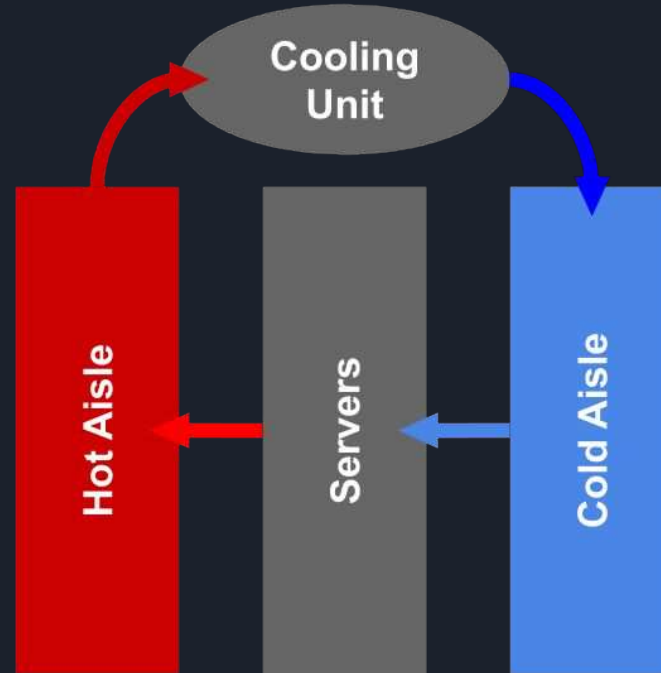
$$T'_c = \frac{f(T_o - T_c)}{m_c}$$

$$T'_h = \frac{f(T_c - T_h)}{m_h} + \frac{P}{c m_h}$$

$$T'_o = \frac{f(T_c - T_h)}{m_h} + \frac{P}{c m_h}$$

Key Properties

- Thermal energy of system remains below an equilibrium point
 - Bounds the problem
 - Useful for proving other properties
- Cold aisle cooler than hot aisle
 - More complicated to prove than expected
 - Relationship can be leveraged for proofs
- **Cold aisle cooler than desired safety temperature**
 - Very difficult: outlet temperature and cold aisle temperature can invert
 - Implies a max temperature for hot aisle





Key results

- Proved safety property for a simple single-aisle system
- Proved some properties (but not safety) for a double-aisle system with a very simple controller
 - Complex relationships among multiple variables
 - Likely needs additional invariants



Future Work

- Complete proof and prototype a monitor
 - Combine with machine learning controllers
 - Verify model's usefulness on real data
- Make the controller more permissive
- Improve the model's accuracy
 - Distributed Server Model
 - More inputs
 - More complex physics



Conclusion

- Formal verification of a monitor complements current machine learning approaches well
- Proofs for even simple real-world models can be complicated and require significantly more work
- Differential dynamic logic is good for guaranteeing safety properties



Thank you!



$$\dot{y} = \left(\frac{f}{2m_1} + \frac{f}{2m_2} \right) y$$
$$\dot{f} = - \left(\frac{f}{2m_1} + \frac{f}{2m_2} \right) z$$

```
t:=0;
{
  T_c = (f + (T_c - T_c))/m_c;
  T_h = (f + (T_h - T_h))/m_h + P/(c * m_h);
  T_c = (f + (T_c - T_c))/m_c + P/(c * m_c);
  f = 1;
  if t < stop;
  if T_c < COP_max;
  if T_h > COP_min;
}
```