

# Towards Efficient Quantifier Elimination in Mathematica

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# What is quantifier elimination (QE)?

- Example:  $\forall x_1 \exists x_2 (x_1 + x_2 = 0)$  becomes “True”

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<sup>1</sup>Adapted from Pablo Parillo's lecture notes

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- Example:  $\forall x_1 \exists x_2 (x_1 + x_2 = 0)$  becomes “True”
- Example:  $\forall x_1 \forall x_2 (x_1^2 + ax_2^2 \leq 1) \rightarrow ax_1^2 - a^2x_1x_2 + 2 \geq 0$  becomes  $(a \geq 0) \wedge (a^3 - 8a - 16) \leq 0$ <sup>1</sup>

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## Two seminal results

- Quantifier elimination is decidable (Tarski, 1930).
- Cylindrical algebraic decomposition (CAD) algorithm (Collins, 1975)



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- Safety proofs of hybrid systems reduce to real arithmetic questions.
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- Safety proofs of hybrid systems reduce to real arithmetic questions.
- Efficient QE is key for efficient proofs.
- KeYmaera X outsources QE calls to Mathematica.



# Our Goal

Improve quantifier elimination in Mathematica, with a view towards increasing the efficiency of KeYmaera X.



# Our Approach

- Focus on the universal fragment of decision problems

$$\forall x_1, \forall x_2, \dots, \forall x_k \phi(x_1, \dots, x_k)$$



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- Because we can put formulas into CNF, we focus on disjunctions.

$$\begin{array}{ccc} \forall x_1, \dots, x_n (\phi_1 \wedge \phi_2) & & \\ \swarrow \quad \searrow & & \\ \forall x_1, \dots, x_n \phi_1 & & \forall x_1, \dots, x_n \phi_2 \end{array}$$

# Our Approach

Two sub-approaches:

- Analyze the structures of the input polynomials.
- Analyze the structures of the polynomials computed during CAD.

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# Odd Degree Variables

## Example 1

$$\forall v, w, x, y, z (-6 - 7v^2w^3x + 9v^2w^3xyz + 6v^3w^2z^2 > 0 \vee \\ 6 - 5v^2w^2xy + 7v^3wx^3yz + vy^3z > 0)$$

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- Notice that  $v$  has odd degree in both polynomials.
- Find values of  $w, x, y, z$  so that  $6w^2z^2$  and  $7wx^3yz$  are either both positive or both negative. (E.g.  $w = x = y = z = 1$ .)

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- Return FALSE with “ $v$  is  $-\infty$ , all other variables are 1” as a witness.

## Set a Variable to 0

## Example 2

$$\forall v, w, x, y, z (1 - 10vw^2y - v^3x^3yz^2 - v^3wx^2yz^3 > 0 \vee \\ -7 + 9w^2xy^3z + 8v^2w^3xz^2 > 0)$$



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- Notice that we can find values of  $v, x, y,$  and  $z$  so that  $-7 \leq 0$  and  $1 - v^3x^3yz^2 \leq 0$ . (E.g.  $v = x = y = z = 1$ .)

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## Example 3

$$\forall v, w, x, y, z - 10 - 5v^2w^3y^2z - 10vxyz^3 > 0 \vee$$
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- Notice that both have negative real coefficients.
- Return FALSE with “All variables are  $\infty$  (i.e. set all variables equal and sufficiently large)” as a witness.

# Analyze Leading Coefficients

## Example 4

$$\forall v, w, z, w, y \left( -8 + 8v^2w^3z + 6v^2w^3y^2z - 7vx^3yz^2 > 0 \vee \right. \\ \left. -5 - 10v^2w^2x^2 + 7vwx^3yz - 7v^3wxz^2 > 0 \right)$$



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- Notice that we can find values of  $v, x, y,$  and  $x$  to make both of these negative. (E.g.  $y = x = w = v = 1.$ )

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- Return FALSE with “ $z = \infty$ , all other variables are 1” as a witness.

# Polynomial Properties

- For each of these examples, we have a corresponding theorem.
- We implemented an algorithm for each theorem in Mathematica.

# Benchmarks

We tested on several sets of benchmarks.

- 328 decision problems from KeYmaera 3.<sup>2</sup>

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- 44 decision problems from Mulligan et. al.<sup>3</sup>

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- 44 decision problems from Mulligan et. al.<sup>3</sup>
- Decision problems we generate ourselves.

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# Performance

	Avg Runtime	Max Runtime	# decided	# with ==
KeYmaera 3	0.12 s			
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KeYmaera 3	0.12 s	5.32 s	91 of 328	
Mulligan et. al.	0.35 s	5.29 s	2 of 44	



Thanks to  
BooleanConvert!

# Performance

Our algorithms do not apply



	Avg Runtime	Max Runtime	# decided	# with ==
KeYmaera 3	0.12 s	5.32 s	91 of 328	120 of 328
Mulligan et. al.	0.35 s	5.29 s	2 of 44	19 of 44
Our algorithms				

# Performance

- The third set of benchmarks is not fixed.
- Set of polynomials pseudorandomly generated each time our testing method is called.
- Generates many examples which our heuristics very quickly determine are false and on which Mathematica runs slowly.

# Performance

In fact, **all of** Examples 1–4 were generated by running our testing method and finding an example where our algorithms return almost instantly but Mathematica stalls.

# Conclusion

GOAL: Develop a set of algorithms to improve  
QE in Mathematica (for the universal fragment of  
decision procedures)



Exploit algebraic structure

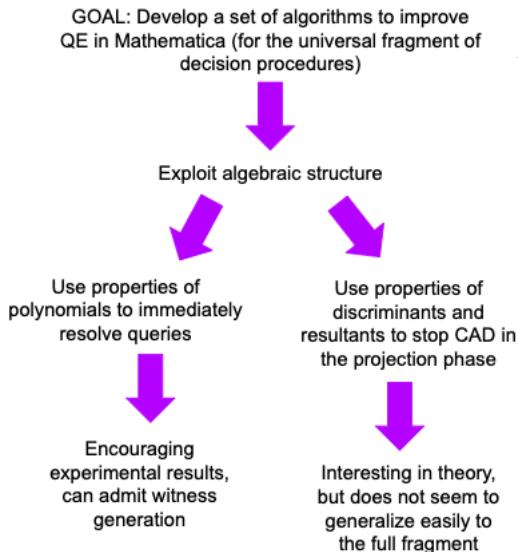


Use properties of  
polynomials to immediately  
resolve queries



Encouraging  
experimental results,  
can admit witness  
generation

# Conclusion



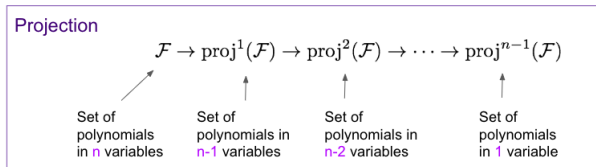
# CAD

- Input: A set of polynomials in  $n$  variables
- Output: A sign-invariant decomposition of  $\mathbb{R}^n$  composed of **cells** and a **sample point** for each cell (called a CAD)
- The signs of the polynomials at the (finitely many) sample points are representative of the signs of the polynomials on the entirety of  $\mathbb{R}^n$



## CAD

- Two phases: projection and lifting

**Lifting**

Sign-invariant cells and  
sample points for

 $\mathcal{F}$ 

(the CAD)

← ... ←

Sign-invariant cells and  
sample points for

 $\text{proj}^{n-2}(\mathcal{F})$ 

←

Sign-invariant cells and  
sample points for

 $\text{proj}^{n-1}(\mathcal{F})$

# CAD

- The projection operator is designed so that the projections of different cells are either disjoint or identical
- So if CAD  $A$  is lifted from CAD  $B$ , the cells in CAD  $A$  are cylindrically arranged over the cells in CAD  $B$

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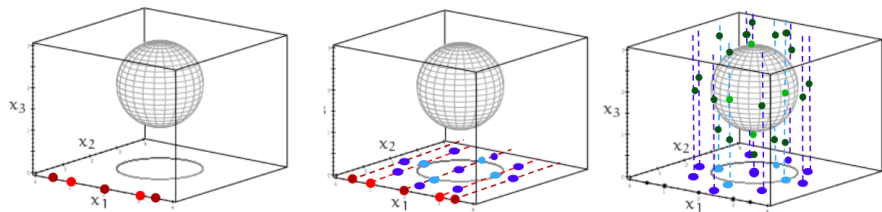


Figure 1: Modified from Jirstrand<sup>4</sup>

<sup>4</sup>Jirstrand, *Algebraic methods for inequality constraints in control*, Ph.D. thesis (1998)

# CAD over the years

Many people have worked to improve CAD.

- Brown, McCallum: Improved projection operator
- Collins, Hong: Partial CAD
- McCallum: Full dimensional CAD
- Strzeboński: GCAD

# Properties of Discriminants and Resultants

## Multiple Zeros of $f$

Given a polynomial  $f \in \mathbb{R}[x_1, \dots, x_n]$ , if  $\text{Disc}(f, x_1)(q) = 0$  for some point  $q \in \mathbb{R}^{n-1}$  and the leading coefficient of  $x_1$  in  $f$  (which is a polynomial in  $\mathbb{R}[x_2, \dots, x_n]$ ) evaluated at  $q$  is nonzero, then the decision problem  $\forall x_1, \dots, x_n f(x_1, \dots, x_n) > 0$  is false.

## Common Roots of $f$ and $g$

Given  $f, g \in \mathbb{R}[x_1, \dots, x_n]$ , if there exists a point  $q \in \mathbb{R}^{n-1}$  where  $\text{Res}(f, g, x_1)(q) = 0$  and the leading coefficients of  $x_1$  in  $f$  and  $g$  (which are polynomials in  $\mathbb{R}[x_2, \dots, x_n]$ ) are nonzero when evaluated at  $q$ , then the decision problem  $\forall x_1, \dots, x_n (f(x_1, \dots, x_n) > 0 \vee g(x_1, \dots, x_n) > 0)$  is false.

# Properties of Discriminants and Resultants

## Discriminant Lemma

Take a polynomial  $f = a_{2n}x^{2n} + \cdots + a_0$  with real coefficients and  $a_{2n} \neq 0$  (i.e., an even-degree polynomial). If  $n$  is even and the discriminant of  $f$  is  $\leq 0$ , then  $f$  has real roots, and if  $n$  is odd and the discriminant of  $f$  is  $\geq 0$ , then  $f$  has real roots.

# Discriminant Algorithm

**DECISION PROBLEM:** For all  $x_1, \dots, x_n$   $f(x_1, \dots, x_n) > 0$

