

05: Dynamical Systems & Dynamic Axioms

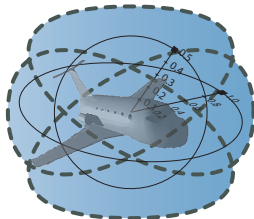
15-424: Foundations of Cyber-Physical Systems

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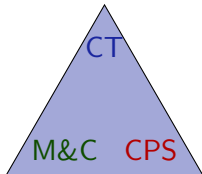
- 1 Learning Objectives
- 2 Approach
- 3 Reminder: Compositional Semantics
- 4 Bouncing Ball
- 5 Intermediate Conditions for CPS
- 6 Dynamic Axioms for Dynamical Systems
- 7 Intermediate Conditions versus Sequential Compositions
- 8 First Bouncing Ball Proof
- 9 Summary

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Learning Objectives

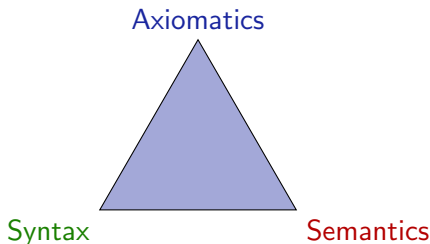
Dynamical Systems & Dynamic Axioms

rigorous reasoning about CPS
dL as verification language



cyber+physics interaction
relate discrete+continuous

align semantics+reasoning
operational CPS effects



Syntax defines the notation

What problems are we allowed to write down?

Semantics what carries meaning.

What real or mathematical objects does the syntax stand for?

Axiomatics internalizes semantic relations into universal syntactic transformations.

How does the semantics of A relate to semantics of $A \wedge B$, syntactically? If A is true, is $A \wedge B$ true, too? Conversely?

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Logical guiding principle: Compositionality

- 1 Every CPS is modeled by a hybrid program (or game ...)
- 2 All hybrid programs are combinations of simpler hybrid programs (by a program operator such as \cup and $;$ and $*$)
- 3 All CPS can be analyzed if only we identify one suitable analysis technique for each operator.

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Definition (Hybrid program semantics)

$([\![\cdot]\!] : \text{HP} \rightarrow \wp(\mathcal{S} \times \mathcal{S}))$

$$[\![x := e]\!] = \{(\omega, \nu) : \nu = \omega \text{ except } \nu[x] = \omega[e]\}$$

$$[\![?Q]\!] = \{(\omega, \omega) : \omega \in [\![Q]\!]\}$$

$$[\![x' = f(x)]\!] = \{(\varphi(0), \varphi(r)) : \varphi \models x' = f(x) \text{ for some duration } r\}$$

$$[\![\alpha \cup \beta]\!] = [\![\alpha]\!] \cup [\![\beta]\!]$$

$$[\![\alpha; \beta]\!] = [\![\alpha]\!] \circ [\![\beta]\!]$$

$$[\![\alpha^*]\!] = \bigcup_{n \in \mathbb{N}} [\![\alpha^n]\!]$$

Definition (dL semantics)

$([\![\cdot]\!] : \text{Fml} \rightarrow \wp(\mathcal{S}))$

$$[\![\theta \geq \eta]\!] = \{\omega : \omega[\theta] \geq \omega[\eta]\}$$

$$[\![\neg\phi]\!] = ([\![\phi]\!])^c$$

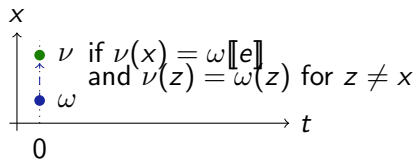
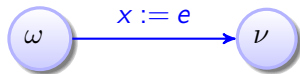
$$[\![\phi \wedge \psi]\!] = [\![\phi]\!] \cap [\![\psi]\!]$$

$$[\![\langle \alpha \rangle \phi]\!] = [\![\alpha]\!] \circ [\![\phi]\!] = \{\omega : \nu \in [\![\phi]\!] \text{ for some } \nu : (\omega, \nu) \in [\![\alpha]\!]\}$$

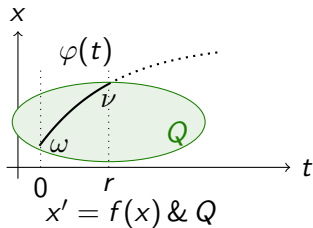
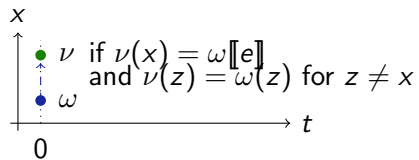
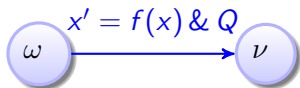
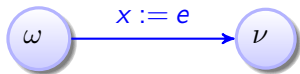
$$[\![[\alpha]\phi]\!] = [\![\neg\langle \alpha \rangle \neg\phi]\!] = \{\omega : \nu \in [\![\phi]\!] \text{ for all } \nu : (\omega, \nu) \in [\![\alpha]\!]\}$$

$$[\![\exists x \phi]\!] = \{\omega : \omega_x^r \in [\![\phi]\!] \text{ for some } r \in \mathbb{R}\}$$

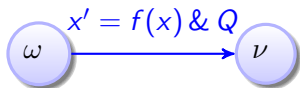
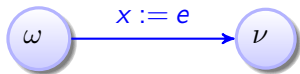
Differential Dynamic Logic dL: Transition Semantics



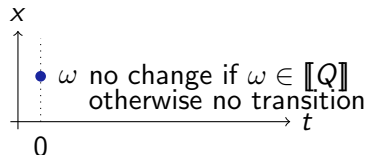
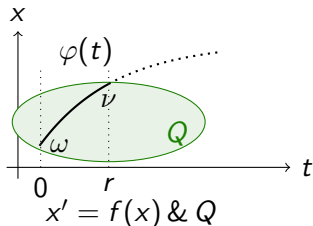
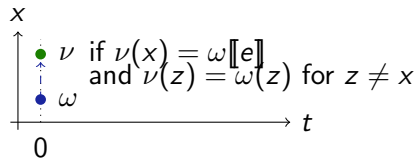
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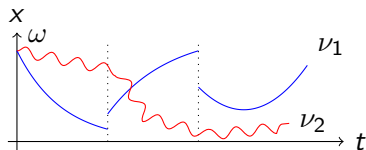
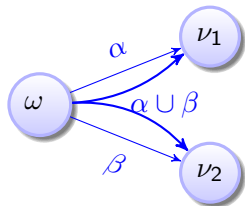
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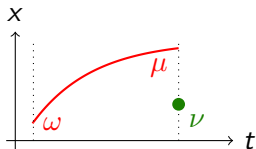
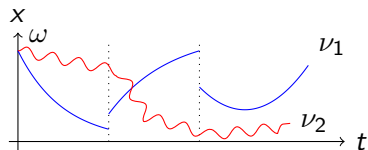
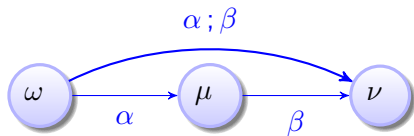
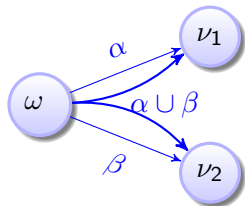
if $\omega \in \llbracket Q \rrbracket$



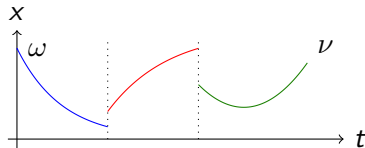
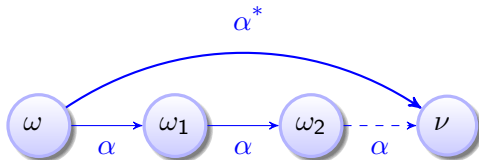
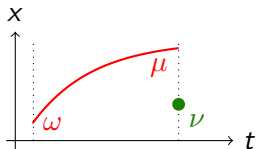
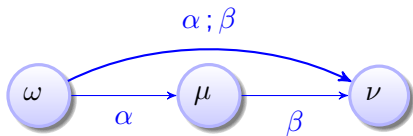
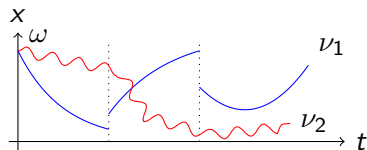
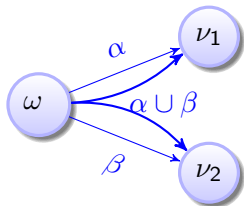
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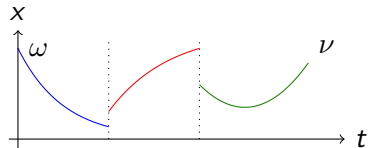
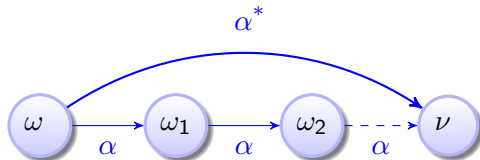
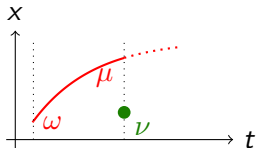
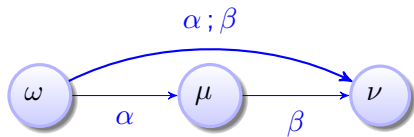
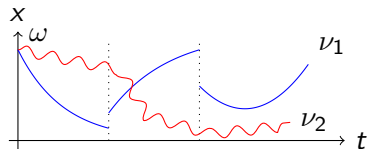
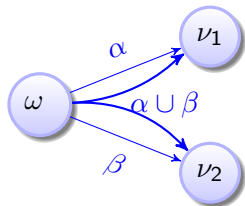
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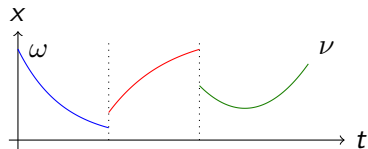
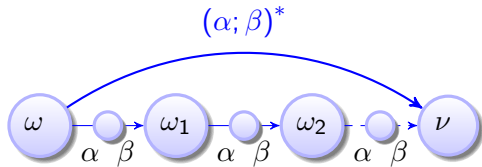
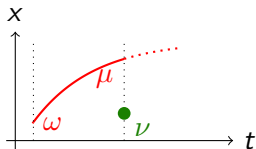
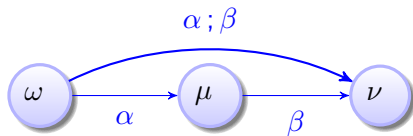
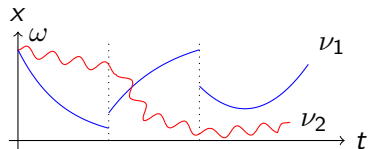
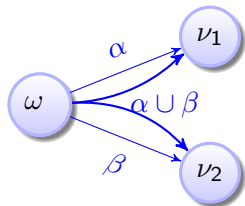
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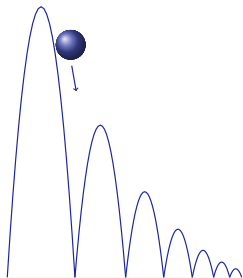


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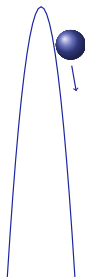
Conjecture: Quantum the Acrophobic Bouncing Ball



Example (Quantum the Bouncing Ball)

$$0 \leq x \wedge x = H \wedge v = 0 \wedge g > 0 \wedge 1 \geq c \geq 0 \rightarrow$$
$$[(x' = v, v' = -g \ \& \ x \geq 0; (?x = 0; v := -cv \cup ?x \neq 0))^*] (0 \leq x \wedge x \leq H)$$

Conjecture: Quantum the Acrophobic Bouncing Ball



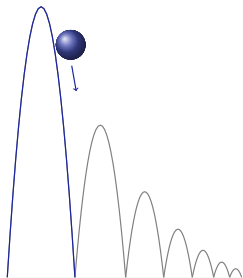
Example (Quantum the Bouncing Ball)

(Single-hop)

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Removing the repetition grotesquely changes the behavior to a single hop

Conjecture: Quantum the Acrophobic Bouncing Ball



Example (Quantum the Bouncing Ball)

(Single-hop)

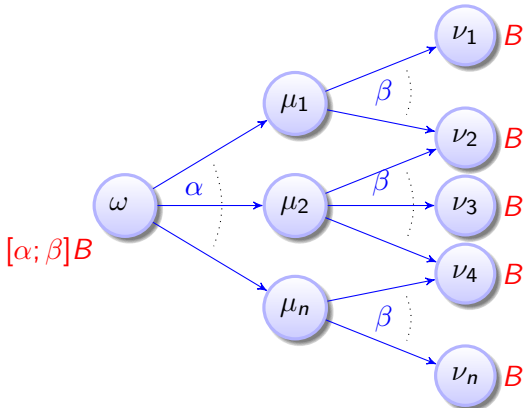
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Removing the repetition grotesquely changes the behavior to a single hop

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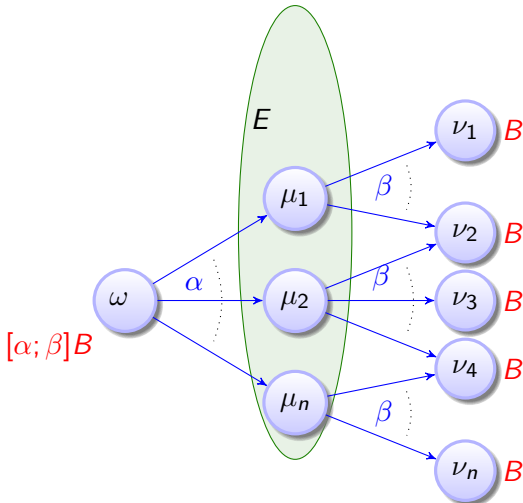
Intermediate Conditions for CPS

HM; $\frac{}{A \rightarrow [\alpha; \beta]B}$



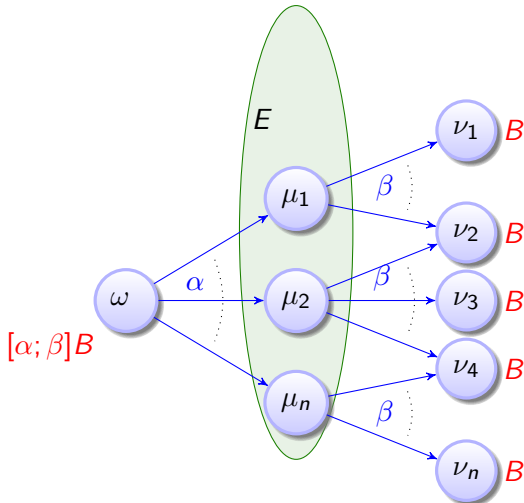
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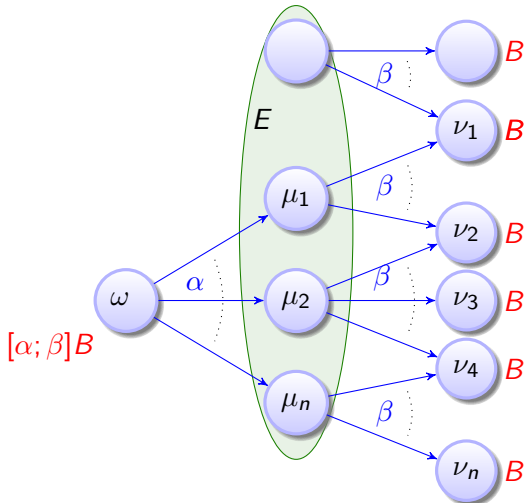
Intermediate Conditions for CPS

$$\text{HM}; \frac{A \rightarrow [\alpha]E \quad E \rightarrow [\beta]B}{A \rightarrow [\alpha; \beta]B}$$



Intermediate Conditions for CPS

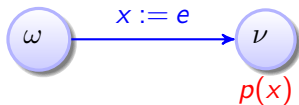
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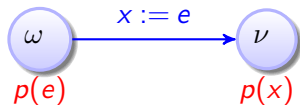
Dynamic Axioms for Dynamical Systems

$[:=] \quad [x := e]p(x) \leftrightarrow$



Dynamic Axioms for Dynamical Systems

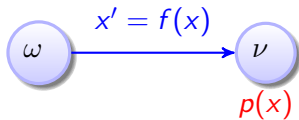
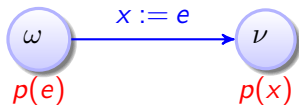
$[\text{:=}] \quad [x := e]p(x) \leftrightarrow p(e)$



Dynamic Axioms for Dynamical Systems

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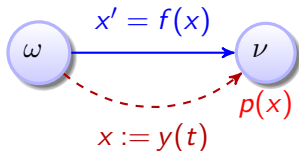
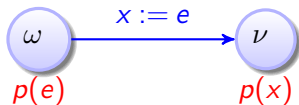
$$['] \quad [x' = f(x)]p(x) \leftrightarrow$$



Dynamic Axioms for Dynamical Systems

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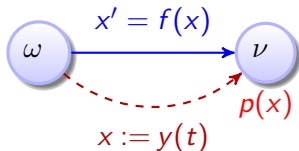
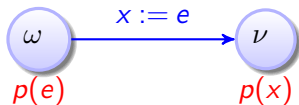
$$['] \quad [x' = f(x)]p(x) \leftrightarrow [x := y(t)]p(x)$$



Dynamic Axioms for Dynamical Systems

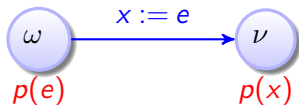
$$[:=] \quad [x := e]p(x) \leftrightarrow p(e)$$

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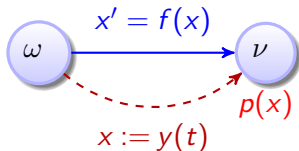


Dynamic Axioms for Dynamical Systems

$$[:=] \quad [x := e]p(x) \leftrightarrow p(e)$$



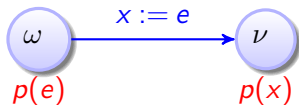
$$['] \quad [x' = f(x)]p(x) \leftrightarrow \forall t \geq 0 [x := y(t)]p(x)$$



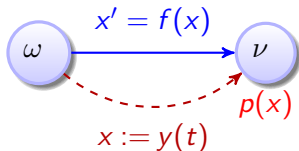
$$['] \quad [x' = f(x) \& q(x)]p(x) \leftrightarrow \forall t \geq 0 ([x := y(t)]p(x))$$

Dynamic Axioms for Dynamical Systems

$$[:=] \quad [x := e]p(x) \leftrightarrow p(e)$$



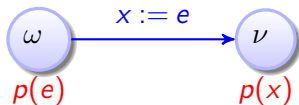
$$['] \quad [x' = f(x)]p(x) \leftrightarrow \forall t \geq 0 [x := y(t)]p(x)$$



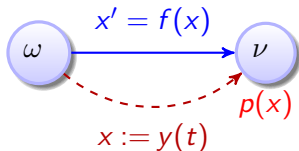
$$['] \quad [x' = f(x) \ \& \ q(x)]p(x) \leftrightarrow \forall t \geq 0 (\forall 0 \leq s \leq t q(y(s)) \rightarrow [x := y(t)]p(x))$$

Dynamic Axioms for Dynamical Systems

$$[:=] [x := e]p(x) \leftrightarrow p(e)$$



$$['] [x' = f(x)]p(x) \leftrightarrow \forall t \geq 0 [x := y(t)]p(x)$$



$$['] [x' = f(x) \& q(x)]p(x) \leftrightarrow \forall t \geq 0 (\forall 0 \leq s \leq t q(y(s)) \rightarrow [x := y(t)]p(x))$$

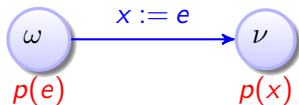
$$[?] [?Q]P \leftrightarrow$$



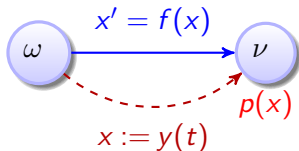
if $\omega \in [Q]$

Dynamic Axioms for Dynamical Systems

$$[:=] \quad [x := e]p(x) \leftrightarrow p(e)$$



$$['] \quad [x' = f(x)]p(x) \leftrightarrow \forall t \geq 0 [x := y(t)]p(x)$$



$$['] \quad [x' = f(x) \ \& \ q(x)]p(x) \leftrightarrow \forall t \geq 0 (\forall 0 \leq s \leq t q(y(s)) \rightarrow [x := y(t)]p(x))$$

$$[?] \quad [?Q]P \leftrightarrow (Q \rightarrow P)$$

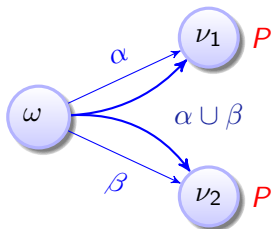


if $\omega \in [Q]$

compositional semantics \Rightarrow compositional rules!

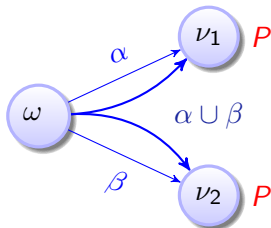
Dynamic Axioms for Dynamical Systems

$[U] [\alpha U \beta]P \leftrightarrow$



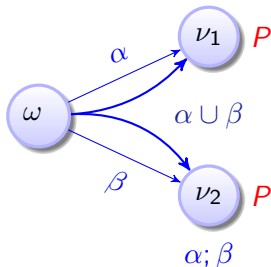
Dynamic Axioms for Dynamical Systems

$$[U] \quad [\alpha \cup \beta]P \leftrightarrow [\alpha]P \wedge [\beta]P$$

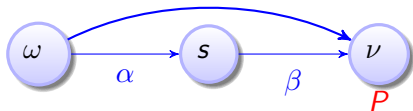


Dynamic Axioms for Dynamical Systems

$$[U] \quad [\alpha \cup \beta]P \leftrightarrow [\alpha]P \wedge [\beta]P$$

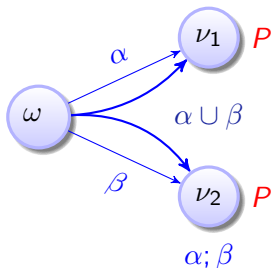


$$[:] \quad [\alpha; \beta]P \leftrightarrow$$

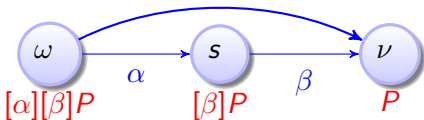


Dynamic Axioms for Dynamical Systems

$$[\cup] \quad [\alpha \cup \beta]P \leftrightarrow [\alpha]P \wedge [\beta]P$$

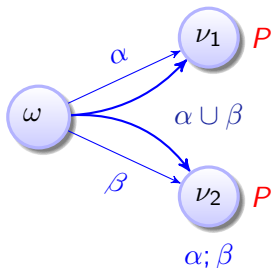


$$[;] \quad [\alpha; \beta]P \leftrightarrow [\alpha][\beta]P$$

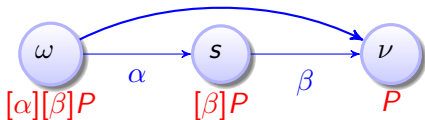


Dynamic Axioms for Dynamical Systems

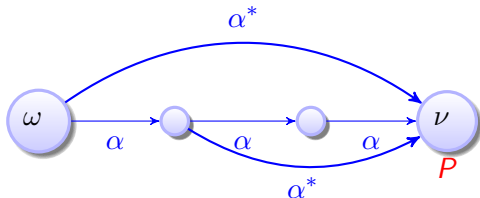
$$[\cup] \quad [\alpha \cup \beta]P \leftrightarrow [\alpha]P \wedge [\beta]P$$



$$[;] \quad [\alpha; \beta]P \leftrightarrow [\alpha][\beta]P$$

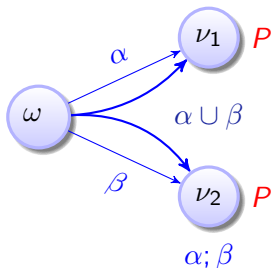


$$[*] \quad [\alpha^*]P \leftrightarrow$$

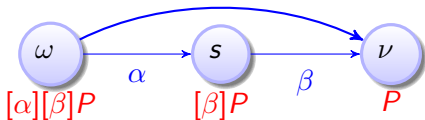


Dynamic Axioms for Dynamical Systems

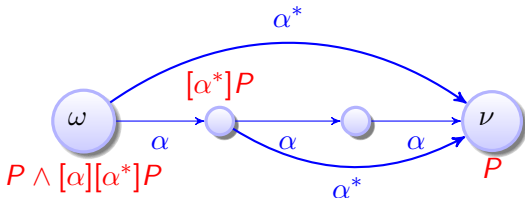
$$[U] \quad [\alpha \cup \beta]P \leftrightarrow [\alpha]P \wedge [\beta]P$$



$$[;] \quad [\alpha; \beta]P \leftrightarrow [\alpha][\beta]P$$



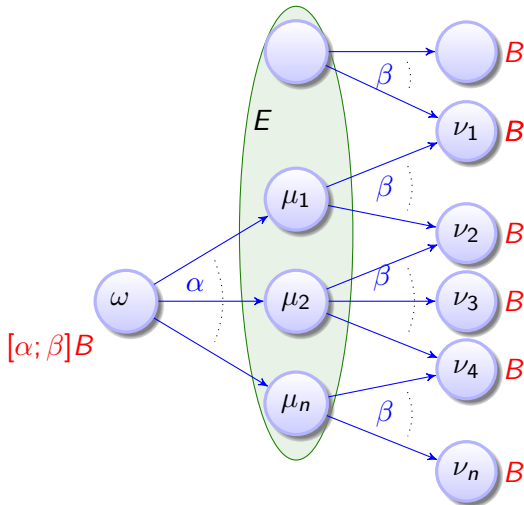
$$[*] \quad [\alpha^*]P \leftrightarrow P \wedge [\alpha][\alpha^*]P$$



- 1 Learning Objectives
- 2 Approach
- 3 Reminder: Compositional Semantics
- 4 Bouncing Ball
- 5 Intermediate Conditions for CPS
- 6 Dynamic Axioms for Dynamical Systems
- 7 Intermediate Conditions versus Sequential Compositions**
- 8 First Bouncing Ball Proof
- 9 Summary

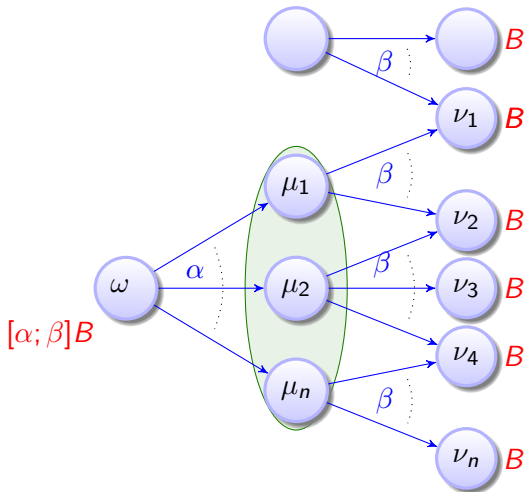
Intermediate Conditions vs. Sequential Compositions

$$\text{HM}; \frac{A \rightarrow [\alpha]E \quad E \rightarrow [\beta]B}{A \rightarrow [\alpha; \beta]B}$$



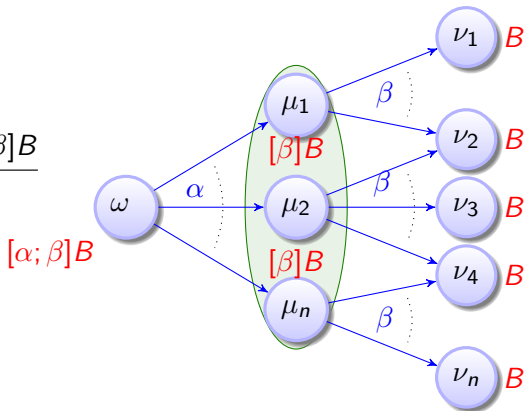
Intermediate Conditions vs. Sequential Compositions

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Intermediate Conditions vs. Sequential Compositions

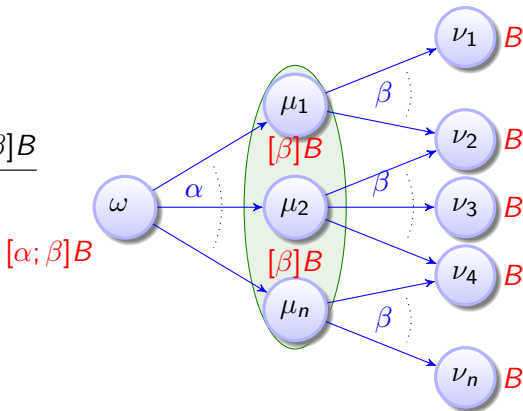
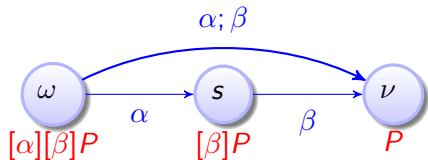
$$\text{HM}; \frac{A \rightarrow [\alpha][\beta]B \quad [\beta]B \rightarrow [\beta]B}{A \rightarrow [\alpha; \beta]B}$$



Intermediate Conditions vs. Sequential Compositions

$$[;] \quad [\alpha; \beta]P \leftrightarrow [\alpha][\beta]P$$

$$\text{HM}; \quad \frac{A \rightarrow [\alpha][\beta]B \quad [\beta]B \rightarrow [\beta]B}{A \rightarrow [\alpha; \beta]B}$$



Developed on the board:

- ① Soundness of axioms
- ② Example-driven sketch of single-hop bouncing ball proof

See lecture notes for details [1].

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A Proof of a Short Single-hop Bouncing Ball

$$[i] \frac{}{A \vdash [x'' = -g; (?x = 0; v := -cv \cup ?x \geq 0)]B(x,v)}$$

$$A \stackrel{\text{def}}{\equiv} 0 \leq x \wedge x = H \wedge v = 0 \wedge g > 0 \wedge 1 \geq c \geq 0$$

$$B(x,v) \stackrel{\text{def}}{\equiv} 0 \leq x \wedge x \leq H$$

$$(x'' = -g) \stackrel{\text{def}}{\equiv} (x' = v, v' = -g)$$

A Proof of a Short Single-hop Bouncing Ball

$$\frac{[U] \quad A \vdash [x'' = -g][?x = 0; v := -cv \cup ?x \geq 0]B(x,v)}{[I] \quad A \vdash [x'' = -g; (?x = 0; v := -cv \cup ?x \geq 0)]B(x,v)}$$
$$A \stackrel{\text{def}}{\equiv} 0 \leq x \wedge x = H \wedge v = 0 \wedge g > 0 \wedge 1 \geq c \geq 0$$
$$B(x,v) \stackrel{\text{def}}{\equiv} 0 \leq x \wedge x \leq H$$
$$(x'' = -g) \stackrel{\text{def}}{\equiv} (x' = v, v' = -g)$$

A Proof of a Short Single-hop Bouncing Ball

$$\frac{[i] \quad A \vdash [x'' = -g]([?x = 0; v := -cv]B(x,v) \wedge [?x \geq 0]B(x,v))}{[U] \quad A \vdash [x'' = -g][?x = 0; v := -cv \cup ?x \geq 0]B(x,v)}$$

$$\frac{[U] \quad A \vdash [x'' = -g][?x = 0; v := -cv \cup ?x \geq 0]B(x,v)}{[i] \quad A \vdash [x'' = -g; (?x = 0; v := -cv \cup ?x \geq 0)]B(x,v)}$$

$$A \stackrel{\text{def}}{=} 0 \leq x \wedge x = H \wedge v = 0 \wedge g > 0 \wedge 1 \geq c \geq 0$$

$$B(x,v) \stackrel{\text{def}}{=} 0 \leq x \wedge x \leq H$$

$$(x'' = -g) \stackrel{\text{def}}{=} (x' = v, v' = -g)$$

A Proof of a Short Single-hop Bouncing Ball

$$\frac{[?],[?]}{A \vdash [x'' = -g]([\text{?}x = 0][v := -cv]B(x,v) \wedge [\text{?}x \geq 0]B(x,v))}$$

$$\frac{[;]}{A \vdash [x'' = -g]([\text{?}x = 0; v := -cv]B(x,v) \wedge [\text{?}x \geq 0]B(x,v))}$$

$$\frac{[\cup]}{A \vdash [x'' = -g][\text{?}x = 0; v := -cv \cup \text{?}x \geq 0]B(x,v)}$$

$$\frac{[;]}{A \vdash [x'' = -g; (\text{?}x = 0; v := -cv \cup \text{?}x \geq 0)]B(x,v)}$$

$$A \stackrel{\text{def}}{\equiv} 0 \leq x \wedge x = H \wedge v = 0 \wedge g > 0 \wedge 1 \geq c \geq 0$$

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A Proof of a Short Single-hop Bouncing Ball

$$\begin{array}{c} \frac{}{[:=] A \vdash [x'' = -g]((x = 0 \rightarrow [v := -cv]B(x,v)) \wedge (x \geq 0 \rightarrow B(x,v)))} \\ \frac{}{[?],[?] A \vdash [x'' = -g]([?x = 0][v := -cv]B(x,v) \wedge [?x \geq 0]B(x,v))} \\ \frac{}{[;] A \vdash [x'' = -g]([?x = 0; v := -cv]B(x,v) \wedge [?x \geq 0]B(x,v))} \\ \frac{}{[\cup] A \vdash [x'' = -g][?x = 0; v := -cv \cup ?x \geq 0]B(x,v)} \\ \frac{}{[;] A \vdash [x'' = -g; (?x = 0; v := -cv \cup ?x \geq 0)]B(x,v)} \end{array}$$

$$A \stackrel{\text{def}}{\equiv} 0 \leq x \wedge x = H \wedge v = 0 \wedge g > 0 \wedge 1 \geq c \geq 0$$

$$B(x,v) \stackrel{\text{def}}{\equiv} 0 \leq x \wedge x \leq H$$

$$(x'' = -g) \stackrel{\text{def}}{\equiv} (x' = v, v' = -g)$$

A Proof of a Short Single-hop Bouncing Ball

$$\begin{array}{c} \frac{[?]}{A \vdash [x'' = -g]((x = 0 \rightarrow B(x, -cv)) \wedge (x \geq 0 \rightarrow B(x, v)))} \\ \frac{[:=]}{A \vdash [x'' = -g]((x = 0 \rightarrow [v := -cv]B(x, v)) \wedge (x \geq 0 \rightarrow B(x, v)))} \\ \frac{[?], [?]}{A \vdash [x'' = -g]([?x = 0][v := -cv]B(x, v) \wedge [?x \geq 0]B(x, v))} \\ \frac{[;]}{A \vdash [x'' = -g]([?x = 0; v := -cv]B(x, v) \wedge [?x \geq 0]B(x, v))} \\ \frac{[\cup]}{A \vdash [x'' = -g][?x = 0; v := -cv \cup ?x \geq 0]B(x, v)} \\ \frac{[;]}{A \vdash [x'' = -g; (?x = 0; v := -cv \cup ?x \geq 0)]B(x, v)} \end{array}$$

$$A \stackrel{\text{def}}{=} 0 \leq x \wedge x = H \wedge v = 0 \wedge g > 0 \wedge 1 \geq c \geq 0$$

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$$(x'' = -g) \stackrel{\text{def}}{=} (x' = v, v' = -g)$$

A Proof of a Short Single-hop Bouncing Ball

$$\begin{array}{l} \text{[i]} \frac{}{A \vdash \forall t \geq 0 [x := H - \frac{g}{2}t^2; v := -gt] ((x=0 \rightarrow B(x, -cv)) \wedge (x \geq 0 \rightarrow B(x, v)))} \\ \text{[!]} \frac{}{A \vdash [x'' = -g] ((x=0 \rightarrow B(x, -cv)) \wedge (x \geq 0 \rightarrow B(x, v)))} \\ \text{[:=]} \frac{}{A \vdash [x'' = -g] ((x=0 \rightarrow [v := -cv]B(x, v)) \wedge (x \geq 0 \rightarrow B(x, v)))} \\ \text{[?], [?]} \frac{}{A \vdash [x'' = -g] ([?x = 0][v := -cv]B(x, v) \wedge [?x \geq 0]B(x, v))} \\ \text{[i]} \frac{}{A \vdash [x'' = -g] ([?x = 0; v := -cv]B(x, v) \wedge [?x \geq 0]B(x, v))} \\ \text{[U]} \frac{}{A \vdash [x'' = -g][?x = 0; v := -cv \cup ?x \geq 0]B(x, v)} \\ \text{[i]} \frac{}{A \vdash [x'' = -g; (?x = 0; v := -cv \cup ?x \geq 0)]B(x, v)} \end{array}$$

$$A \stackrel{\text{def}}{=} 0 \leq x \wedge x = H \wedge v = 0 \wedge g > 0 \wedge 1 \geq c \geq 0$$

$$B(x, v) \stackrel{\text{def}}{=} 0 \leq x \wedge x \leq H$$

$$(x'' = -g) \stackrel{\text{def}}{=} (x' = v, v' = -g)$$

A Proof of a Short Single-hop Bouncing Ball

$$\begin{array}{l}
 \text{[:=]} \frac{}{A \vdash \forall t \geq 0 [x := H - \frac{g}{2}t^2][v := -gt] ((x=0 \rightarrow B(x,-cv)) \wedge (x \geq 0 \rightarrow B(x,v)))} \\
 \text{[;]} \frac{}{A \vdash \forall t \geq 0 [x := H - \frac{g}{2}t^2; v := -gt] ((x=0 \rightarrow B(x,-cv)) \wedge (x \geq 0 \rightarrow B(x,v)))} \\
 \text{[']} \frac{}{A \vdash [x'' = -g] ((x = 0 \rightarrow B(x,-cv)) \wedge (x \geq 0 \rightarrow B(x,v)))} \\
 \text{[:=]} \frac{}{A \vdash [x'' = -g] ((x = 0 \rightarrow [v := -cv]B(x,v)) \wedge (x \geq 0 \rightarrow B(x,v)))} \\
 \text{[?],[?]} \frac{}{A \vdash [x'' = -g] ([?x = 0][v := -cv]B(x,v) \wedge [?x \geq 0]B(x,v))} \\
 \text{[;]} \frac{}{A \vdash [x'' = -g] ([?x = 0; v := -cv]B(x,v) \wedge [?x \geq 0]B(x,v))} \\
 \text{[U]} \frac{}{A \vdash [x'' = -g][?x = 0; v := -cv \cup ?x \geq 0]B(x,v)} \\
 \text{[;]} \frac{}{A \vdash [x'' = -g; (?x = 0; v := -cv \cup ?x \geq 0)]B(x,v)}
 \end{array}$$

$$A \stackrel{\text{def}}{\equiv} 0 \leq x \wedge x = H \wedge v = 0 \wedge g > 0 \wedge 1 \geq c \geq 0$$

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A Proof of a Short Single-hop Bouncing Ball

$$\begin{array}{l}
\text{[:=]} \frac{}{A \vdash \forall t \geq 0 [x := H - \frac{g}{2}t^2] ((x=0 \rightarrow B(x, -c(-gt))) \wedge (x \geq 0 \rightarrow B(x, -gt)))} \\
\text{[:=]} \frac{}{A \vdash \forall t \geq 0 [x := H - \frac{g}{2}t^2] [v := -gt] ((x=0 \rightarrow B(x, -cv)) \wedge (x \geq 0 \rightarrow B(x, v)))} \\
\text{[;]} \frac{}{A \vdash \forall t \geq 0 [x := H - \frac{g}{2}t^2; v := -gt] ((x=0 \rightarrow B(x, -cv)) \wedge (x \geq 0 \rightarrow B(x, v)))} \\
\text{[']} \frac{}{A \vdash [x'' = -g] ((x = 0 \rightarrow B(x, -cv)) \wedge (x \geq 0 \rightarrow B(x, v)))} \\
\text{[:=]} \frac{}{A \vdash [x'' = -g] ((x = 0 \rightarrow [v := -cv] B(x, v)) \wedge (x \geq 0 \rightarrow B(x, v)))} \\
\text{[?],[?]} \frac{}{A \vdash [x'' = -g] ([?x = 0][v := -cv] B(x, v) \wedge [?x \geq 0] B(x, v))} \\
\text{[;]} \frac{}{A \vdash [x'' = -g] ([?x = 0; v := -cv] B(x, v) \wedge [?x \geq 0] B(x, v))} \\
\text{[U]} \frac{}{A \vdash [x'' = -g][?x = 0; v := -cv \cup ?x \geq 0] B(x, v)} \\
\text{[;]} \frac{}{A \vdash [x'' = -g; (?x = 0; v := -cv \cup ?x \geq 0)] B(x, v)}
\end{array}$$

$$A \stackrel{\text{def}}{\equiv} 0 \leq x \wedge x = H \wedge v = 0 \wedge g > 0 \wedge 1 \geq c \geq 0$$

$$B(x, v) \stackrel{\text{def}}{\equiv} 0 \leq x \wedge x \leq H$$

$$(x'' = -g) \stackrel{\text{def}}{\equiv} (x' = v, v' = -g)$$

A Proof of a Short Single-hop Bouncing Ball

$$\begin{array}{l}
 \frac{A \vdash \forall t \geq 0 ((H - \frac{g}{2}t^2 = 0 \rightarrow B(H - \frac{g}{2}t^2, -c(-gt))) \wedge (H - \frac{g}{2}t^2 \geq 0 \rightarrow B(H - \frac{g}{2}t^2, -gt)))}{[:=] A \vdash \forall t \geq 0 [x := H - \frac{g}{2}t^2] ((x=0 \rightarrow B(x, -c(-gt))) \wedge (x \geq 0 \rightarrow B(x, -gt)))} \\
 \frac{[:=] A \vdash \forall t \geq 0 [x := H - \frac{g}{2}t^2][v := -gt] ((x=0 \rightarrow B(x, -cv)) \wedge (x \geq 0 \rightarrow B(x, v)))}{[:=] A \vdash \forall t \geq 0 [x := H - \frac{g}{2}t^2; v := -gt] ((x=0 \rightarrow B(x, -cv)) \wedge (x \geq 0 \rightarrow B(x, v)))} \\
 \frac{[i] A \vdash \forall t \geq 0 [x := H - \frac{g}{2}t^2; v := -gt] ((x=0 \rightarrow B(x, -cv)) \wedge (x \geq 0 \rightarrow B(x, v)))}{[i] A \vdash [x'' = -g] ((x=0 \rightarrow B(x, -cv)) \wedge (x \geq 0 \rightarrow B(x, v)))} \\
 \frac{[i] A \vdash [x'' = -g] ((x=0 \rightarrow [v := -cv]B(x, v)) \wedge (x \geq 0 \rightarrow B(x, v)))}{[:=] A \vdash [x'' = -g] ((x=0 \rightarrow [v := -cv]B(x, v)) \wedge (x \geq 0 \rightarrow B(x, v)))} \\
 \frac{[i] A \vdash [x'' = -g] ([?x = 0][v := -cv]B(x, v) \wedge [?x \geq 0]B(x, v))}{[?],[?] A \vdash [x'' = -g] ([?x = 0][v := -cv]B(x, v) \wedge [?x \geq 0]B(x, v))} \\
 \frac{[i] A \vdash [x'' = -g] ([?x = 0; v := -cv]B(x, v) \wedge [?x \geq 0]B(x, v))}{[i] A \vdash [x'' = -g] ([?x = 0; v := -cv]B(x, v) \wedge [?x \geq 0]B(x, v))} \\
 \frac{[U] A \vdash [x'' = -g][?x = 0; v := -cv \cup ?x \geq 0]B(x, v)}{[U] A \vdash [x'' = -g][?x = 0; v := -cv \cup ?x \geq 0]B(x, v)} \\
 \frac{[i] A \vdash [x'' = -g; (?x = 0; v := -cv \cup ?x \geq 0)]B(x, v)}{[i] A \vdash [x'' = -g; (?x = 0; v := -cv \cup ?x \geq 0)]B(x, v)}
 \end{array}$$

$$A \stackrel{\text{def}}{=} 0 \leq x \wedge x = H \wedge v = 0 \wedge g > 0 \wedge 1 \geq c \geq 0$$

$$B(x, v) \stackrel{\text{def}}{=} 0 \leq x \wedge x \leq H$$

$$(x'' = -g) \stackrel{\text{def}}{=} (x' = v, v' = -g)$$

A Proof of a Short Single-hop Bouncing Ball

$$\begin{array}{l}
 A \vdash \forall t \geq 0 \left((H - \frac{g}{2}t^2 = 0 \rightarrow B(H - \frac{g}{2}t^2, -c(-gt))) \wedge (H - \frac{g}{2}t^2 \geq 0 \rightarrow B(H - \frac{g}{2}t^2, -gt)) \right) \\
 \hline
 [:=] A \vdash \forall t \geq 0 [x := H - \frac{g}{2}t^2] \left((x=0 \rightarrow B(x, -c(-gt))) \wedge (x \geq 0 \rightarrow B(x, -gt)) \right) \\
 \hline
 [:=] A \vdash \forall t \geq 0 [x := H - \frac{g}{2}t^2][v := -gt] \left((x=0 \rightarrow B(x, -cv)) \wedge (x \geq 0 \rightarrow B(x, v)) \right) \\
 \hline
 [;] A \vdash \forall t \geq 0 [x := H - \frac{g}{2}t^2; v := -gt] \left((x=0 \rightarrow B(x, -cv)) \wedge (x \geq 0 \rightarrow B(x, v)) \right) \\
 \hline
 ['] A \vdash [x'' = -g] \left((x=0 \rightarrow B(x, -cv)) \wedge (x \geq 0 \rightarrow B(x, v)) \right) \\
 \hline
 [:=] A \vdash [x'' = -g] \left((x=0 \rightarrow [v := -cv]B(x, v)) \wedge (x \geq 0 \rightarrow B(x, v)) \right) \\
 \hline
 [?],[?] A \vdash [x'' = -g] \left([?x = 0][v := -cv]B(x, v) \wedge [?x \geq 0]B(x, v) \right) \\
 \hline
 [;] A \vdash [x'' = -g] \left([?x = 0; v := -cv]B(x, v) \wedge [?x \geq 0]B(x, v) \right) \\
 \hline
 [U] A \vdash [x'' = -g][?x = 0; v := -cv \cup ?x \geq 0]B(x, v) \\
 \hline
 [;] A \vdash [x'' = -g; (?x = 0; v := -cv \cup ?x \geq 0)]B(x, v)
 \end{array}$$

$$A \stackrel{\text{def}}{\equiv} 0 \leq x \wedge x = H \wedge v = 0 \wedge g > 0 \wedge 1 \geq c \geq 0$$

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A Proof of a Short Single-hop Bouncing Ball

Resolving abbreviations at the premise yields:

$$\begin{aligned} 0 \leq x \wedge x = H \wedge v = 0 \wedge g > 0 \wedge 1 \geq c \geq 0 \rightarrow \\ \forall t \geq 0 \left(\left(H - \frac{g}{2}t^2 = 0 \rightarrow 0 \leq H - \frac{g}{2}t^2 \wedge H - \frac{g}{2}t^2 \leq H \right) \right. \\ \left. \wedge \left(H - \frac{g}{2}t^2 \geq 0 \rightarrow 0 \leq H - \frac{g}{2}t^2 \wedge H - \frac{g}{2}t^2 \leq H \right) \right) \end{aligned}$$

which is provable by arithmetic (since $g > 0$ and $t^2 \geq 0$).

A Proof of a Short Single-hop Bouncing Ball

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A Proof of a Short Single-hop Bouncing Ball

Resolving abbreviations at the premise yields:

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which is provable by arithmetic (since $g > 0$ and $t^2 \geq 0$).

Exciting!

We have just formally verified our very first CPS!

A Proof of a Short Single-hop Bouncing Ball

Resolving abbreviations at the premise yields:

$$\begin{aligned} 0 \leq x \wedge x = H \wedge v = 0 \wedge g > 0 \wedge 1 \geq c \geq 0 \rightarrow \\ \forall t \geq 0 \left(\left(H - \frac{g}{2}t^2 = 0 \rightarrow 0 \leq H - \frac{g}{2}t^2 \wedge H - \frac{g}{2}t^2 \leq H \right) \right. \\ \left. \wedge \left(H - \frac{g}{2}t^2 \geq 0 \rightarrow 0 \leq H - \frac{g}{2}t^2 \wedge H - \frac{g}{2}t^2 \leq H \right) \right) \end{aligned}$$

which is provable by arithmetic (since $g > 0$ and $t^2 \geq 0$).

Exciting!

We have just formally verified our very first CPS!

Okay, alright, it was a grotesquely simplified single-hop bouncing ball. But the axioms of our proof technique were completely general and not specific to bouncing balls, so they should carry us forward to true CPS.

- 1 Learning Objectives
- 2 Approach
- 3 Reminder: Compositional Semantics
- 4 Bouncing Ball
- 5 Intermediate Conditions for CPS
- 6 Dynamic Axioms for Dynamical Systems
- 7 Intermediate Conditions versus Sequential Compositions
- 8 First Bouncing Ball Proof
- 9 Summary**

$$[:=] [x := e]p(x) \leftrightarrow p(e)$$

$$[?] [?Q]P \leftrightarrow (Q \rightarrow P)$$

$$['] [x' = f(x)]p(x) \leftrightarrow \forall t \geq 0 [x := y(t)]p(x) \quad (y'(t) = f(y))$$

$$[\cup] [\alpha \cup \beta]P \leftrightarrow [\alpha]P \wedge [\beta]P$$

$$[;] [\alpha; \beta]P \leftrightarrow [\alpha][\beta]P$$

$$[*] [\alpha^*]P \leftrightarrow P \wedge [\alpha][\alpha^*]P$$

$$K [\alpha](P \rightarrow Q) \rightarrow ([\alpha]P \rightarrow [\alpha]Q)$$

$$I [\alpha^*](P \rightarrow [\alpha]P) \rightarrow (P \rightarrow [\alpha^*]P)$$

$$C [\alpha^*]\forall v > 0 (P(v) \rightarrow \langle \alpha \rangle P(v-1)) \rightarrow \forall v (P(v) \rightarrow \langle \alpha^* \rangle \exists v \leq 0 P(v))$$



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